



# Statistical Signal Processing Workshop

June 28-30, 2011

## *A Copula based Framework for Distributed Inference*

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# Different Sensors, Diverse Information

**THROUGH-THE-WALL**

**THZ IMAGING**

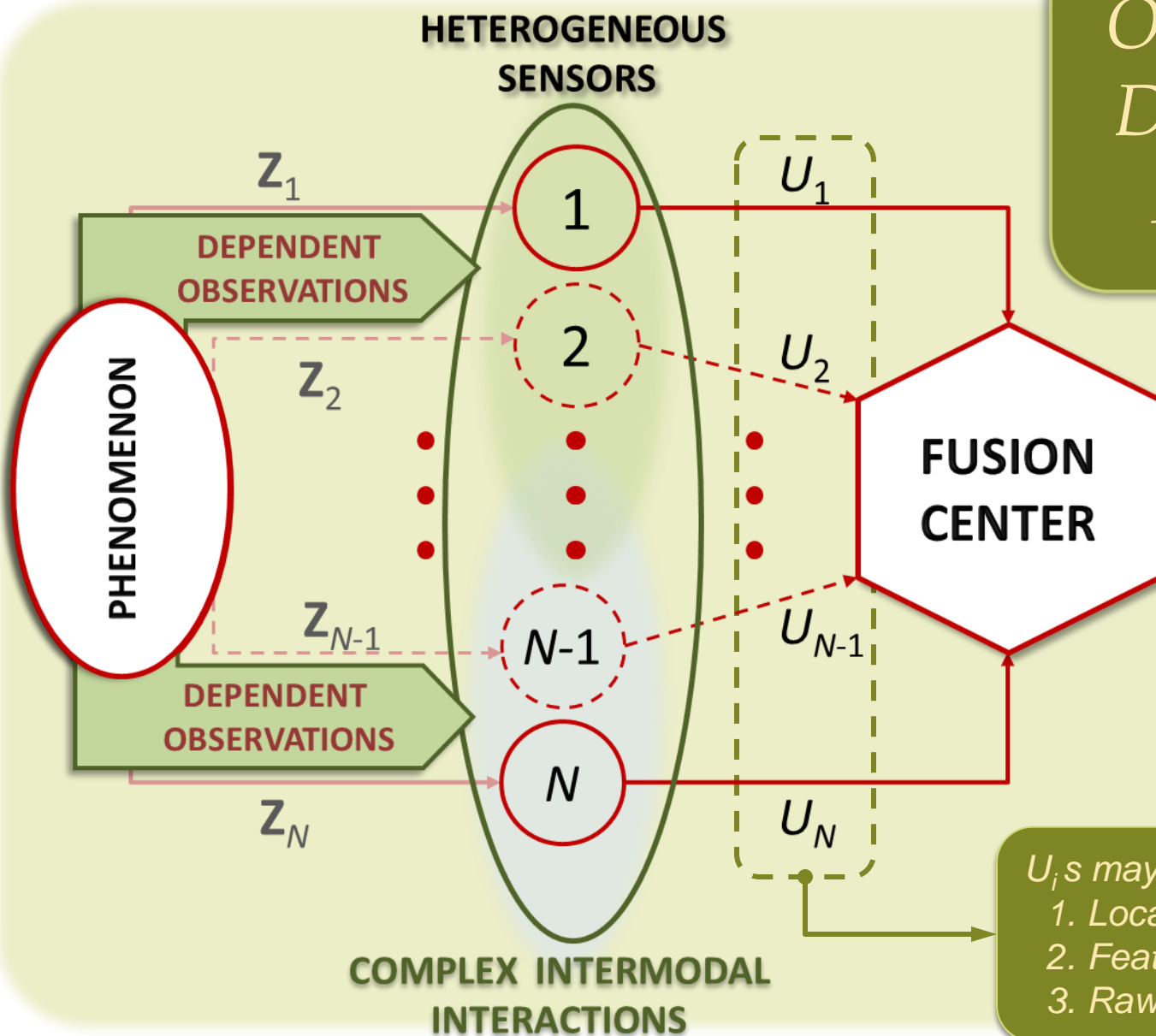
**VIDEO**

**THZ IMAGING**

**SEISMIC**

**ACOUSTIC**

# Overview of Distributed Inference



$U_i$ s may be

1. Local decisions
2. Features
3. Raw signal

# Outline

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- ▶ Introduction
- ▶ Heterogeneity and Dependence
- ▶ Copula theory
- ▶ Signal Detection Using Copulas
- ▶ Copula-based Parameter Estimation (Localization)
- ▶ Classification using copulas
- ▶ *Applications in finance are not considered!*
- ▶ Conclusion

# Previous Work: Signal Processing Using Dependent Observations

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- ▶ Different characterizations of dependence exist, e.g.,
  - ▶ Correlation coefficient – Linear measure of dependence
  - ▶ Information theoretic, e.g., mutual information – Computational difficulties
- ▶ Initial work on *distributed inference* assumed independence for tractability
  - ▶ Distributed detection with dependent observations is an NP-complete problem [*Tsitsiklis & Athans, 1985*]
- ▶ Decision fusion strategies to incorporate correlation among sensor decisions
  - ▶ [*Drakopolous & Lee, 1991*] Assumes correlation coefficients are known
  - ▶ [*Kam et al. 1992*] Bahadur-Lazarsfeld expansion of PDF's
  - ▶ Both approaches assume prior knowledge of joint statistics

Interference with dependent observations: difficult problem  
Proposed solutions: largely problem specific

# Inference Under Dependent Observations: Different Approaches

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- ▶ Non-parametric, learning-based
  - ▶ **HMMs & other graphical models**
    - ▶ M. J. Beal *et al.*, “A Graphical Model for Audio-Visual Object Tracking,” *Trans. PAMI*, July 2003, Vol. 25, No. 7, pp. 828-836.
    - ▶ M. R. Siracusa and J. Fisher III, “Dynamic dependency tests: analysis and applications to multi-modal data association,” in *Proc. AI Stats*, 2007.
  - ▶ **Manifold learning**
    - ▶ S. Lafon, Y. Keller, R. R. Coifman, “Data fusion and multicue data matching by diffusion maps,” *IEEE Trans. PAMI*, vol. 28, no. 11, pp. 1784--1797, Nov. 2006
- ▶ General **information theoretic** framework for multimodal signal processing
  - ▶ T. Butz and J. Thiran, “From error probability to information theoretic (multi- modal) signal processing,” *Elsevier: Signal Processing*, vol. 85, May 2005.

# *Heterogeneity and Dependence*



# Heterogeneous Random Vectors

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## Definition

A random vector  $\mathbf{Z} = [Z_1, Z_2, \dots, Z_N]$  governing the joint statistics of an  $N$ -variate data set can be termed as multimodal or heterogeneous if the marginals  $Z_n$  ( $n = 1, \dots, N$ ) are *non-identically distributed*.

- ▶ For example  $Z_1$  and  $Z_2$  may represent acoustic and video signals/features, respectively
- ▶ Definition is general
  - ▶ Includes independent and identically distributed (iid) marginals

# Models of Dependence

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- ▶ Product distribution

$$\hat{\mathbf{f}}_{\mathbf{Z}}(\mathbf{z}) = \prod_{n=1}^N \mathbf{f}_{Z_n}(z_n) = \mathbf{f}_{\mathbf{Z}}^{\mathbf{m}}(\mathbf{z})$$

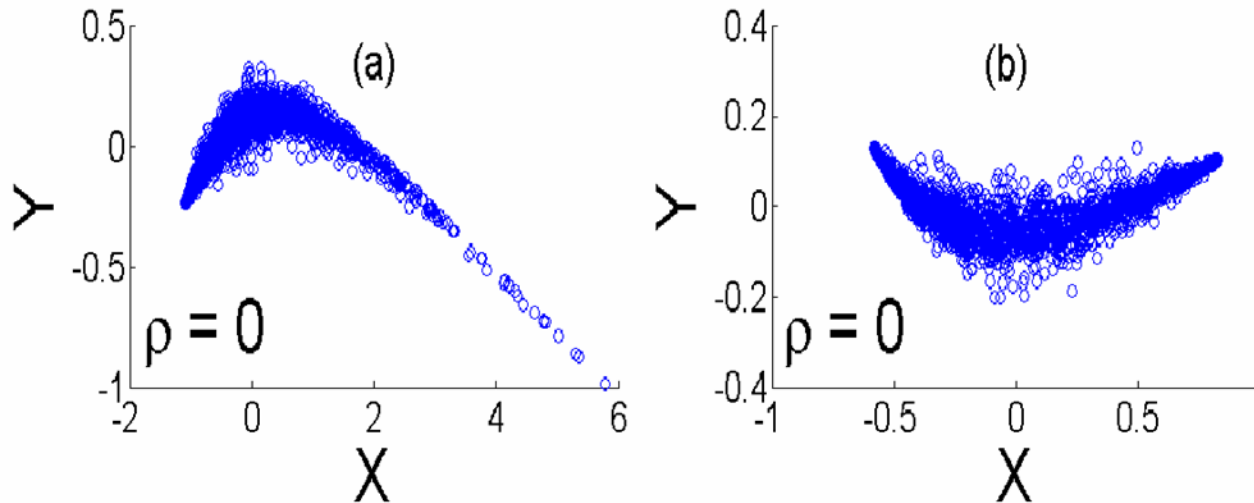
- ▶ Accounts for disparate marginals but not statistical dependence

- ▶ Multivariate Gaussian

- ▶ Cannot model disparate marginals
- ▶ Models dependence through Pearson's  $\rho$
- ▶  $\rho$  measures only *linear* relationship

# Why is $\rho$ insufficient?

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- ▶ Dependence between  $X$  and  $Y$  evident from scatter plot
- ▶ Correlation coefficient is unable to capture this:  $\rho = 0$

# Measures of Dependence

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- ▶ Rank-based (nonparametric) measures: Kendall's  $\tau$  and Spearman's  $\rho^S$  quantify *concordance*
- ▶ For a bivariate random vector  $(X, Y)$  and its realizations  $(X_1, Y_1)$  and  $(X_2, Y_2)$

$$\tau_{X,Y} = \underbrace{P[(X_1 - X_2)(Y_1 - Y_2) > 0]}_{\text{concordance}} - \underbrace{P[(X_1 - X_2)(Y_1 - Y_2) < 0]}_{\text{discordance}}$$

- ▶  $-1 \leq \tau \leq 1$

# Measures of Dependence

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- ▶ Relative entropy: “distance” from product distribution
  - ▶ Multi-information is the multivariate extension of mutual information

$$\mathcal{I}(Z_1; \dots; Z_N) = \int_{\mathbf{z}} \mathbf{f}_{\mathbf{Z}}(\mathbf{z}) \log \left( \frac{\mathbf{f}_{\mathbf{Z}}(\mathbf{z})}{\prod_{i=1}^N \mathbf{f}_{Z_i}(z_i)} \right) d\mathbf{z}$$

- ▶ Normalized measure

$$\delta^* = \sqrt{1 - \exp(-2\mathcal{I})}$$

$$0 \leq \delta^* \leq 1$$

H. Joe, “Relative entropy measures of multivariate dependence,” *Journal of the American Statistical Association*, vol. 84, no. 405, pp. 157-164, 1989

M. Studeny and J. Vejnarova, “The multiinformation function as a tool for measuring stochastic dependence,” in *Learning in Graphical Models (M. I. Jordan ed.)* Kluwer,

Dordrecht 1998, pp. 261-298

# Measures of Dependence

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## ▶ Wyner's Common Information

$$C(X, Y) = \min_{X \rightarrow W \rightarrow Y} I(XY; W)$$

## ▶ Gács and Körner's Common Randomness

### ▶ For random sequences $X^n, Y^n$

▶ Let  $W_1 = f_n(X^n)$  and  $W_2 = g_n(Y^n)$ . Define  $\epsilon_n = \Pr(W_1 \neq W_2)$ .

$$K(X, Y) = \lim_{n \rightarrow \infty, \epsilon_n \rightarrow 0} \sup \frac{1}{n} H(W_1)$$

$$K(X, Y) \leq I(X; Y) \leq C(X, Y)$$

A. D. Wyner, "The common information of two dependent random variables," *IEEE Trans. Inf. Theory*, vol. 21, no. 2, pp. 163-179, March 1975



# *Copula Theory*

Motivation  
Concepts

# Motivation: Why Copulas?

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- ▶ Multimodal sensors provide information diversity: *fusing heterogeneous information is a challenge*
  - ▶ Incommensurate modalities  $\Rightarrow$  Disparate marginal distributions: e.g. audio-video
  - ▶ Complex intermodal interactions  $\rightarrow \rho$  is not sufficient
  - ▶ A *parametric* probabilistic basis for fusion: Joint distribution of sensor observations as an explicit function of parameters
- ▶ *Copula-based approach attempts to address these issues*
  - ▶ Learning-based
    - ▶ Non-parametric, e.g., Hidden Markov Models, Neural Nets, Bayesian Nets
    - ▶ Scenario dependent performance and analysis is difficult
    - ▶ Curse of dimensionality
  - ▶ Simple models are assumed, e.g., independence, joint normality



# Copula Theory

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- ▶ Copulas are functions that *couple* marginals to form a joint distribution
- ▶ Sklar's Theorem is a key result – existence theorem

## Sklar's Theorem

*The joint cumulative distribution function (CDF)  $F_{\mathbf{Z}}(z_1, z_2, \dots, z_N)$  of random variables  $Z_1, Z_2, \dots, Z_N$  are joined by a copula function  $C(\cdot)$  to the respective marginal distributions  $F_{Z_1}(z_1), F_{Z_2}(z_2), \dots, F_{Z_N}(z_N)$  as*

$$F_{\mathbf{Z}}(z_1, z_2, \dots, z_N) = C(F_{Z_1}(z_1), F_{Z_2}(z_2), \dots, F_{Z_N}(z_N))$$

*Further, if the marginals are continuous,  $C(\cdot)$  is unique.*

# Copula Theory

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- ▶ Differentiate the joint CDF to get the joint PDF

$$f(z_1, \dots, z_N) = \left( \prod_{i=1}^N f(z_i) \right) c(F_1(z_1), \dots, F_N(z_N))$$

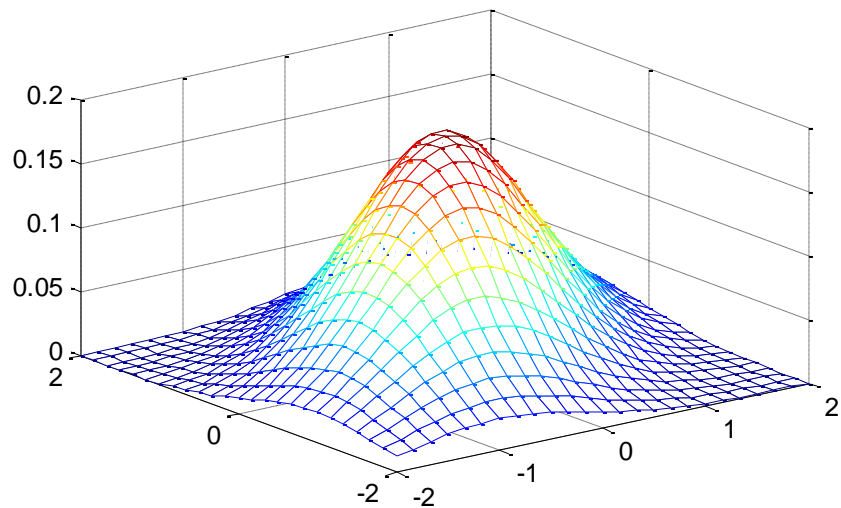
The diagram illustrates the decomposition of the joint PDF into its components. The product density  $\left( \prod_{i=1}^N f(z_i) \right)$  is associated with the label "Product density", which leads to "Independence" via a red arrow. The copula density  $c(F_1(z_1), \dots, F_N(z_N))$  is associated with the label "Copula density". The arguments of the copula density,  $F_1(z_1), \dots, F_N(z_N)$ , are collectively labeled as " $N$  marginals (E.g., from  $N$  sensors)", which leads to "Uniform random variables!" via a red arrow.

# Copula Theory

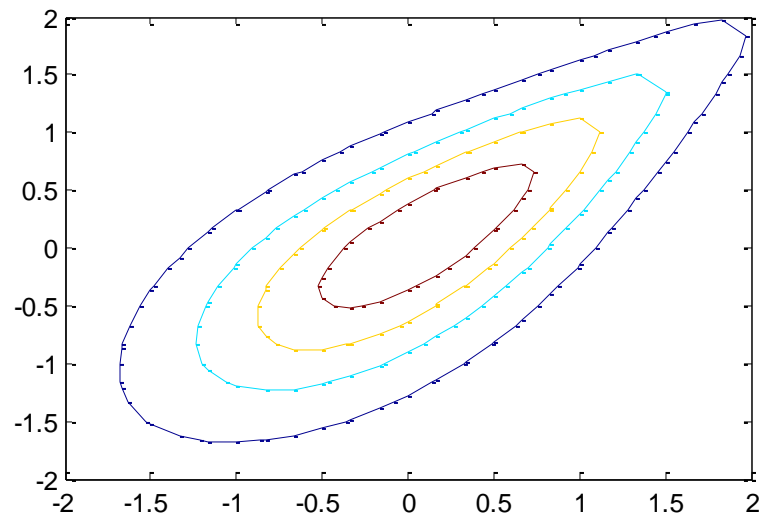
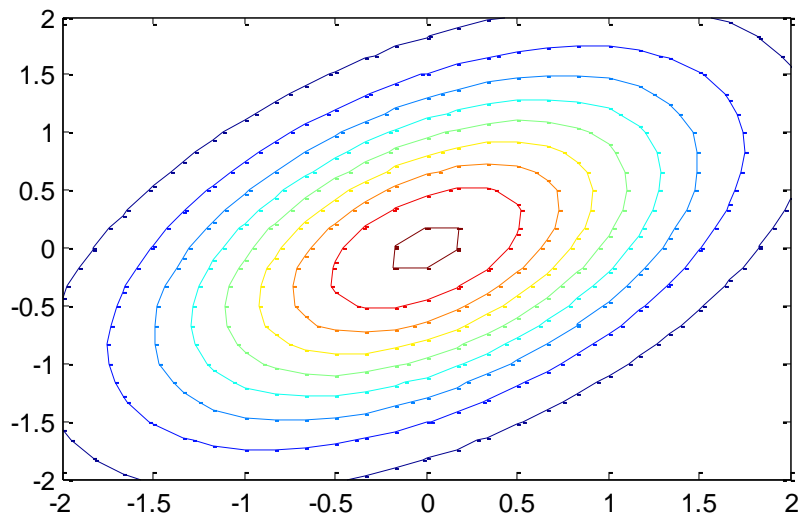
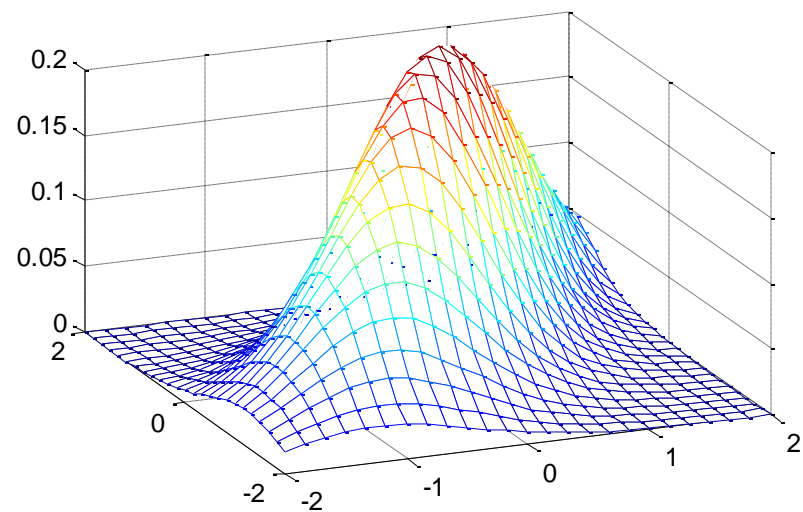
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- ▶ **Several copulas have been proposed**
  - ▶ R. Nelsen, *An Introduction to Copulas*, Springer 1999
  - ▶ Archimedean copulas & Elliptical copulas
- ▶ **Widely used in econometrics**
  - ▶ David Li pioneered the use of the Gaussian Copula
  - ▶ Blamed for the meltdown on Wall Street
  - ▶ Highlights dangers of applying theory without understanding the implications
- ▶ **A pictorial example**
  - ▶ Copulas can characterize skewed dependencies
  - ▶ Copulas can express dependency between marginals that do not share the same support (e.g. Normal and Gamma)

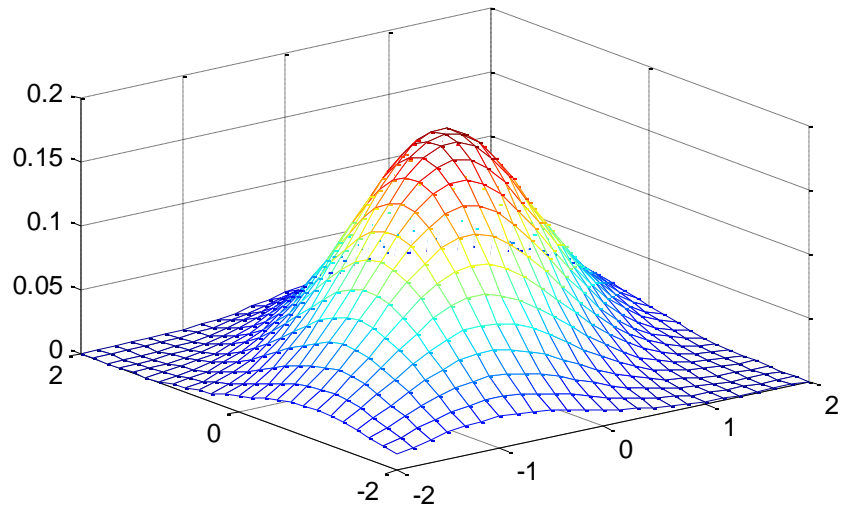
Bivariate Normal,  $\rho = 0.5$



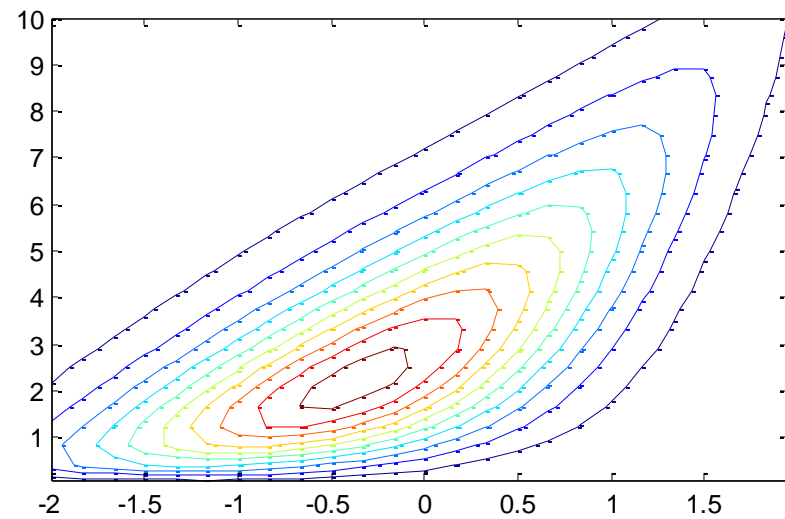
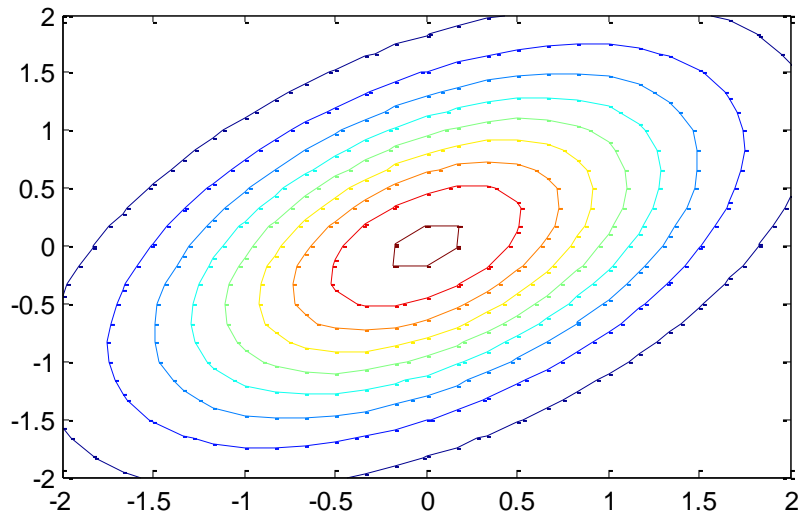
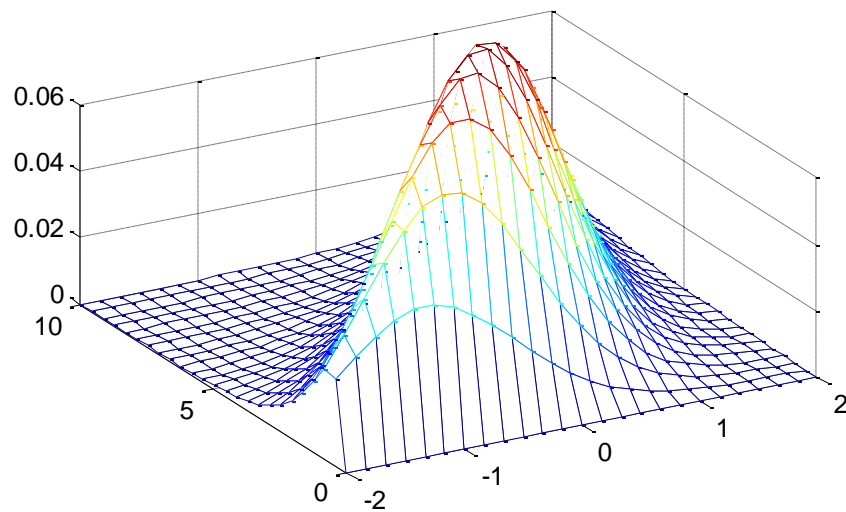
Bivariate density: Normal Marginals,  
Gumbel Copula  $\phi = 2$



Bivariate Normal,  $\rho = 0.5$



Bivariate density: Normal and Gamma Marginals  
Gumbel Copula  $\phi = 2$



# Summary of Copula Functions

- ▶ Copulas are typically defined as a CDF
- ▶ Elliptical copulas: derived from multivariate distributions

$$C^G(\mathbf{k}|\Sigma) = \Phi_{\Sigma}(\Phi^{-1}(k_1), \dots, \Phi^{-1}(k_m)) \quad \text{Gaussian copula}$$

$$C^t(\mathbf{k}|\Sigma, \nu) = t_{\nu, \Sigma}(t_{\nu}^{-1}(k_1), \dots, t_{\nu}^{-1}(k_m)) \quad t\text{-copula}$$

- ▶ Archimedean Copulas

Copula	Generator Function	Parametric Form
Clayton	$\frac{1}{\phi} (k^{-\phi} - 1)$	$\left( \sum_{i=1}^m k_i^{-\phi} - 1 \right)^{-\frac{1}{\phi}}, \phi \in [-1, \infty) \setminus \{0\}$
Frank	$\frac{\exp^{-\phi} - 1}{\exp^{-\phi k} - 1}$	$-\frac{1}{\phi} \ln \left( 1 + \frac{\prod_{i=1}^m (\exp^{-\phi k_i} - 1)}{\exp^{-\phi} - 1} \right), \phi \in \mathbb{R} \setminus \{0\}$
Gumbel	$-\ln k^{\phi}$	$\exp \left\{ - \left( \sum_{i=1}^m (-\ln k_i)^{\phi} \right)^{\frac{1}{\phi}} \right\}, \phi \in [1, \infty)$
Independent	$-\ln k$	$\prod_{i=1}^m k_i$

# Dependence Through Copulas

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- ▶ Amount of dependence is characterized by the parameter vector of the copula functions
    - ▶  $\Sigma, \nu$  for the elliptical copulas
    - ▶  $\phi$  for the Archimedean copulas
- } Collectively denoted as  $\phi$

- ▶ Typically  $\phi$  is unknown: Estimated using

- ▶ Kendall's  $\tau$ : For random variables  $A, B$  and copula  $C$

$$\begin{aligned}k_{\tau}(A, B) &= 4\mathbb{E}\{C_{AB}\} - 1 \\ &= \int \int_{I^2} C_{AB}(u, v) dC_{AB}(u, v) - 1\end{aligned}$$

- ▶ Maximum likelihood

$$\hat{\phi} = \arg \max \sum_i \log c(\mathbf{u}_i | \phi)$$

# Multivariate Copulas

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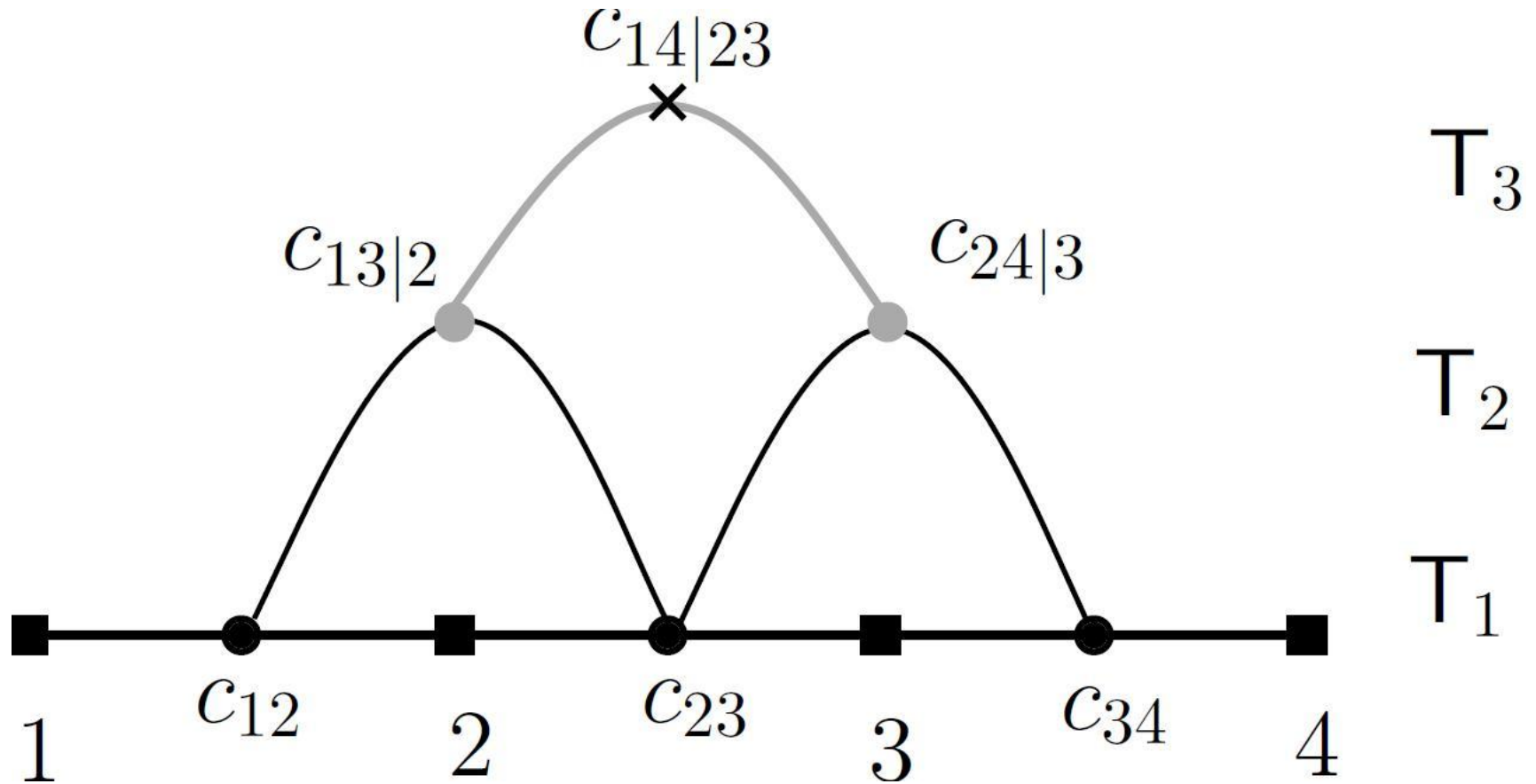
- ▶ A copula density,  $c$ , is defined on  $\mathbb{R}^N$ ,  $N \geq 2$ , however,
  - ▶ Closed-forms are difficult to obtain from the copula CDF
  - ▶ Archimedean copulas: only 1 dependence parameter for  $N > 2$
- ▶ Archimedean and Elliptical copulas
  - ▶ Exchangeability condition
  - ▶ Symmetry

} Limitations
- ▶ Multivariate distribution using *vines*
  - ▶ A vine is a nested set of trees, where the edges of a the  $k$ -th tree are the nodes of the  $(k + 1)$ -th tree
- ▶ We consider a class called *D-vines*

A. Subramanian, A. Sundaresan and P. K. Varshney, "Fusion for the detection of dependent signals using multivariate copulas," in *Proc. 14<sup>th</sup> International Conf. on Information Fusion*, to be published



# Construction of a Multivariate Copula



# Vines: 4 sensor example

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$$\begin{aligned} f(\mathbf{x}) = & \left[ \prod_{i=1}^4 f(x_i) \right] c_{12}(F_1(x_1), F_2(x_2)) \\ & \cdot c_{23}(F_2(x_2), F_3(x_3)) c_{34}(F_3(x_3), F_4(x_4)) \\ & \cdot c_{13|2}(F_{1|2}(x_1|x_2), F_{3|2}(x_3|x_2)) \\ & \cdot c_{24|3}(F_{2|3}(x_2|x_3), F_{4|3}(x_4|x_3)) \\ & \cdot c_{14|23}(F_{1|23}(x_1|x_2, x_3), F_{4|23}(x_4|x_2, x_3)) \end{aligned}$$

Known  $c(\cdot | \phi)$

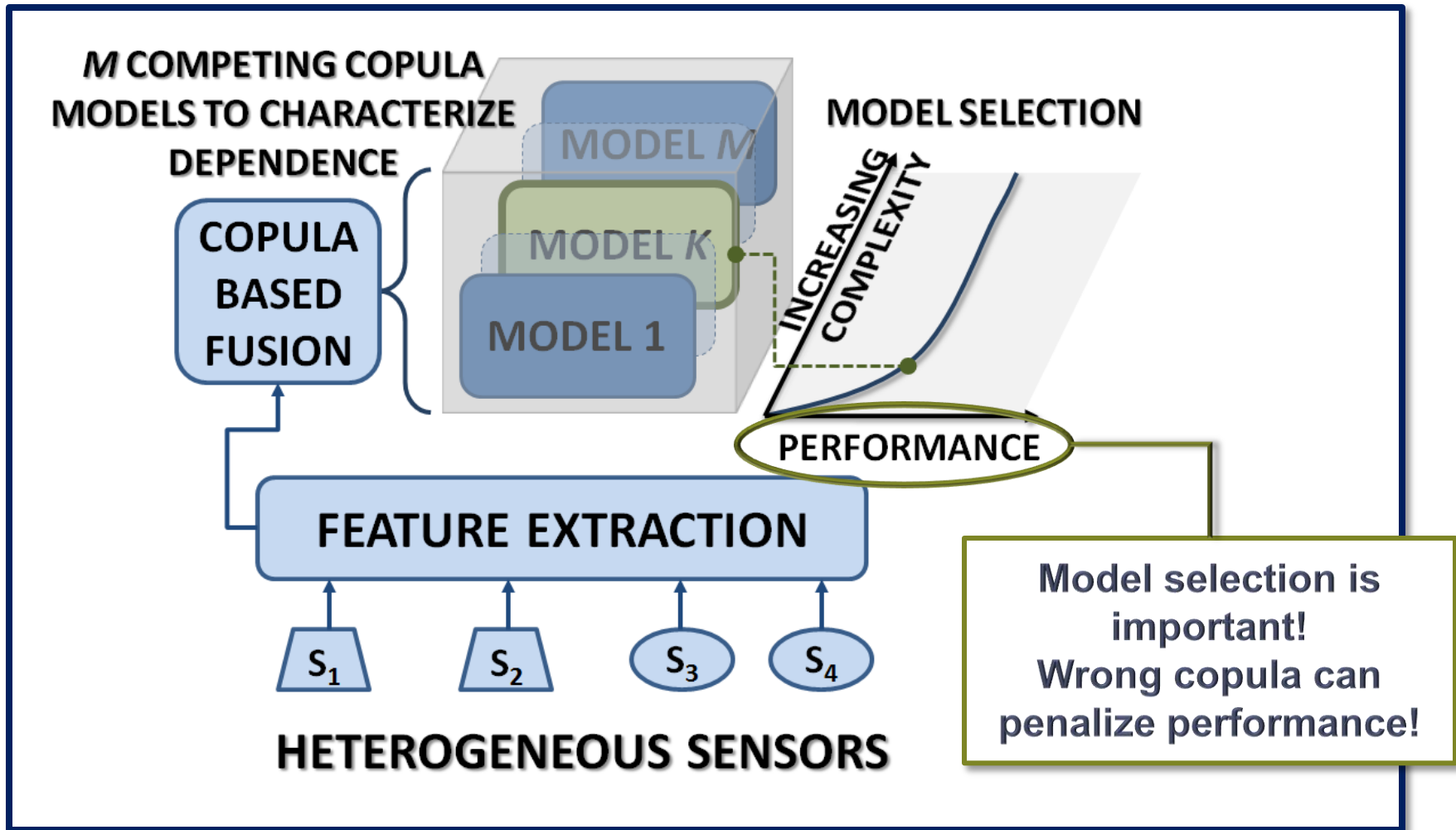
Model Selection  
Find “the best”  $c \in \mathcal{C}$

Sklar’s Theorem, Kendall’s  $\tau$ ,  $\hat{\phi}$ , Vines

$\mathcal{C}$  is a finite set

Copula Library

# Copula-based Inference: Framework



# Copula Selection: MDL-based Approach

- ▶ Criteria based on Minimum Description Length principles
  - ▶ Akaike Information Criterion (AIC)
  - ▶ Bayesian Information Criterion (BIC)
  - ▶ Stochastic Information Criterion (SIC)
  - ▶ Normalized Maximum Likelihood (NML)

▶ Onl'

$$I_k = -2 \log(L_k(\hat{\phi})) + q_k$$

Model index

Joint likelihood

ML Estimate of Copula parameter

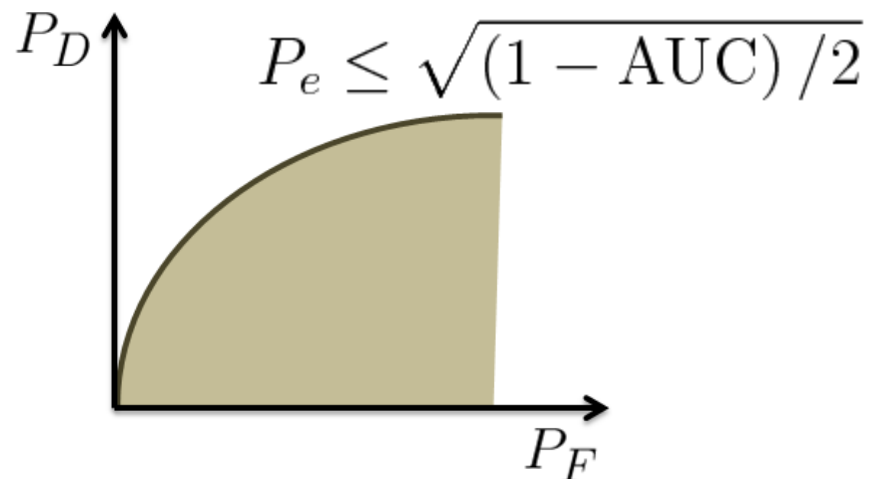
Penalty term proportional to model complexity

# Copula Selection: AUC-based Approach

- ▶ Area Under (receiver operating) Curve
  - ▶ Application specific approach
  - ▶ *Best possible* detector from the available library of models
  - ▶ ROC is best for assessing detector performance → AUC is easier to evaluate
- ▶ Offline approach – training/testing paradigm

$$\text{AUC} = \int_0^1 P_D(P_F) dP_F,$$

$$0 \leq \text{AUC} \leq 1$$





# *Copula Theory Applied to Inference*

Signal Detection  
Localization Estimation  
Classification

# Signal Detection

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- ▶ Binary hypothesis testing problem

$$H_1 : f(\mathbf{z}|\boldsymbol{\theta}_1, \phi_1) = \left[ \prod_i f_i(\cdot|\theta_{1i}) \right] c_1(\mathbf{F}(\cdot|\boldsymbol{\theta}_1)|\phi_1)$$
$$H_0 : g(\mathbf{z}|\boldsymbol{\theta}_0, \phi_0) = \left[ \prod_i g_i(\cdot|\theta_{0i}) \right] c_0(\mathbf{G}(\cdot|\boldsymbol{\theta}_0)|\phi_0)$$

- ▶ General formulation
  - ▶ All distribution parameters are unknown
  - ▶ Estimated using MLE



# Generalized likelihood ratio test

$$\Lambda(\mathbf{z}) = \left[ \sum_i \log \frac{f_i(\cdot | \hat{\theta}_{1i})}{g_i(\cdot | \hat{\theta}_{0i})} \right] + \log \frac{c_1(\cdot | \hat{\phi}_1)}{c_0(\cdot | \hat{\phi}_0)} \underset{H_0}{\overset{H_1}{\gtrless}} \eta$$

GLR under independence

Dependence term

- ▶ Copula based test-statistic decouples marginal and dependency information
- ▶ Information theoretic analysis of copula mismatch and AUC-based results\*

\* S. Iyengar, P. K. Varshney, and T. Damarla, "A parametric copula based framework for hypotheses testing using heterogeneous data," *IEEE Trans. Signal Process.*, Vol 59, No. 5, May 2011, pp. 2308 -

# Indoor Activity Detection

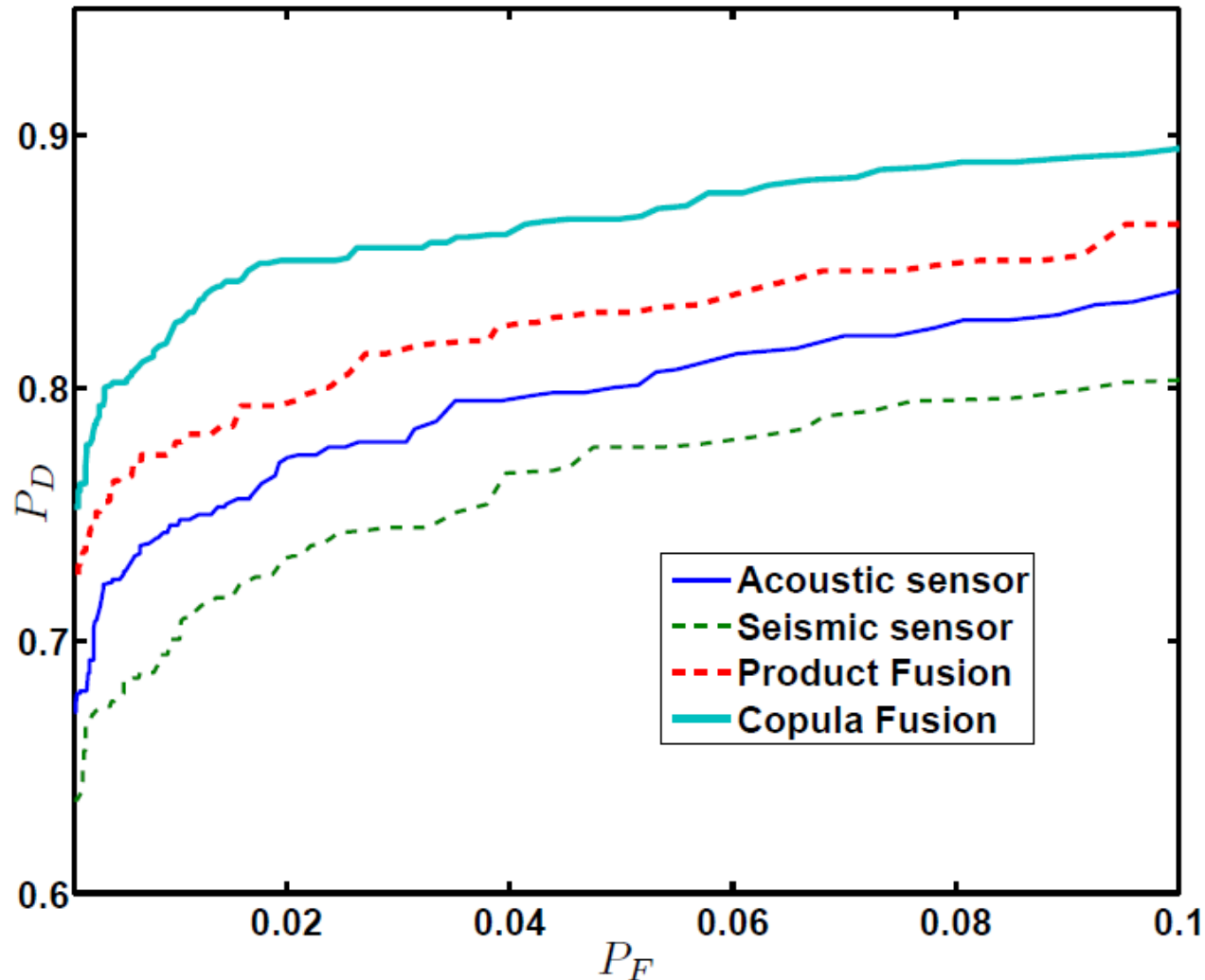


# Indoor Activity Detection

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- ▶ Signals are preprocessed using short-time Fourier Transform (STFT)
- ▶ Canonical Correlation Analysis (CCA) on STFT coefficients
  - ▶ Inter-modal correlation is *emphasized*
  - ▶ Dimensionality reduction:  $\operatorname{argmax}_{\mathbf{a}, \mathbf{b}} \operatorname{Corr}(\mathbf{u} = \mathbf{a}^T \mathbf{X}, \mathbf{v} = \mathbf{b}^T \mathbf{Y})$
- ▶ Marginal distributions fitted using generalized Gaussian
- ▶ Marginal parameters under  $H_0$  assumed known
- ▶ Dependence under  $H_0$  modeled using Gaussian copula

# Results: Seismic-acoustic Fusion



# Distributed Detection: Fusion of correlated local decisions

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- ▶ Binary hypothesis testing problem
  - ▶ Sensors make local decisions
  - ▶ Local decisions are fused at a fusion center
- ▶ No prior knowledge of joint distribution of sensor observations
- ▶ Design problem
  - ▶ Find individual sensor threshold  $\tau_i$
  - ▶ Design optimal fusion rule  $\Lambda(\mathbf{u})$
- ▶ Neyman-Pearson (N-P) framework
- ▶ Temporal independence assumed

# Distributed Detection: Preliminaries

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## ▶ 2 sensor case

- ▶ Over  $N$  time instants from sensors 1 and 2 respectively,

$H_0$  : Source absent  $\rightarrow f(z_{in}|H_0) \quad i = 1, 2; n = 1, \dots, N$

$H_1$  : Source present  $\rightarrow f(z_{in}|H_1) \quad i = 1, 2; n = 1, \dots, N$

Sensor Observations

$$u_{in} = \mathbb{Q}(z_{in}) = \begin{cases} 0 & \text{if } -\infty < z_{in} \leq \tau_i \\ 1 & \text{if } \tau_i \leq z_{in} < \infty \end{cases}$$

Local Sensor Decisions

Sensor Threshold

$$\mathbf{u}_1 = [u_{11}, \dots, u_{1N}]^T \quad \mathbf{u}_2 = [u_{21}, \dots, u_{2N}]^T$$

# Distributed Detection: Dependent Observations

- ▶  $P_{ij} = \Pr(u_{1n} = i, u_{2n} = j | H_1)$
- ▶  $Q_{ij} = \Pr(u_{1n} = i, u_{2n} = j | H_0)$
- ▶ For example,

For binary quantizers  
 $i, j \in \{0,1\}$

$$P_{00} = \int_{z_{1n}=-\infty}^{\tau_1} \int_{z_{2n}=-\infty}^{\tau_2} f(z_{1n}, z_{2n} | H_1) dz_{1n} dz_{2n}$$

$$Q_{00} = \int_{z_{1n}=-\infty}^{\tau_1} \int_{z_{2n}=-\infty}^{\tau_2} f(z_{1n}, z_{2n} | H_0) dz_{1n} dz_{2n}$$

*Observations may not be conditionally independent*

$$\left[ \prod_i f(z_{in} | H_m) \right]_{m=0,1}$$

Copula term  
 $c_m(F(z_{1n}), F(z_{2n}) | \phi)$

# Distributed Detection: Fusion Statistic (Likelihood Ratio)

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$$\log \Lambda(\mathbf{u}) = C_1 \sum_{n=1}^N u_{1n} + C_2 \sum_{n=1}^N u_{2n} + C_3 \sum_{i=n}^N u_{1n} u_{2n}$$

Chair-Varshney  
Fusion Statistic  
*Conditional independence  
term*

Cross-product Term  
*Accounts for correlated  
observations*

$$C_1 = \log \frac{P_{10} Q_{00}}{P_{00} Q_{10}} \quad C_2 = \log \frac{P_{01} Q_{00}}{P_{00} Q_{01}} \quad C_3 = \log \frac{P_{00} P_{11} Q_{01} Q_{10}}{P_{01} P_{10} Q_{00} Q_{11}}$$



# Distributed Detection: Remarks

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- ▶ Test statistic: Asymptotically normal
  - ▶ Used for calculating  $P_D$  and optimal thresholds
- ▶  $L$ -sensor case is similarly solved\*
- ▶ Discussion assumed known  $\phi$ , use MLE if unknown\*

\*A. Sundaresan, P. K. Varshney, and N. S. V. Rao, "Copula-based fusion of correlated decisions," *IEEE Trans. Aerosp. Electron. Syst.*, vol. 47, no. 1, pp. 454–471, 2011

# Distributed Detection Example: Radiation Detection

## ▶ Two models

1. Poisson model in Gaussian noise

$$s_{in}^j \mid \lambda_{ij} \sim \text{Poisson}(\lambda_{ij})$$

2. Hierarchical Poisson-Gamma model

$$\lambda_{ij} \mid \alpha_{ij}, \beta_{ij} \sim \text{Gamma}(\alpha_{ij}, \beta_{ij})$$

## ▶ Binary hypothesis testing

$$H_0 : z_{in} = s_{in}^0 + w_{in}$$

$$H_1 : z_{in} = s_{in}^1 + w_{in}$$

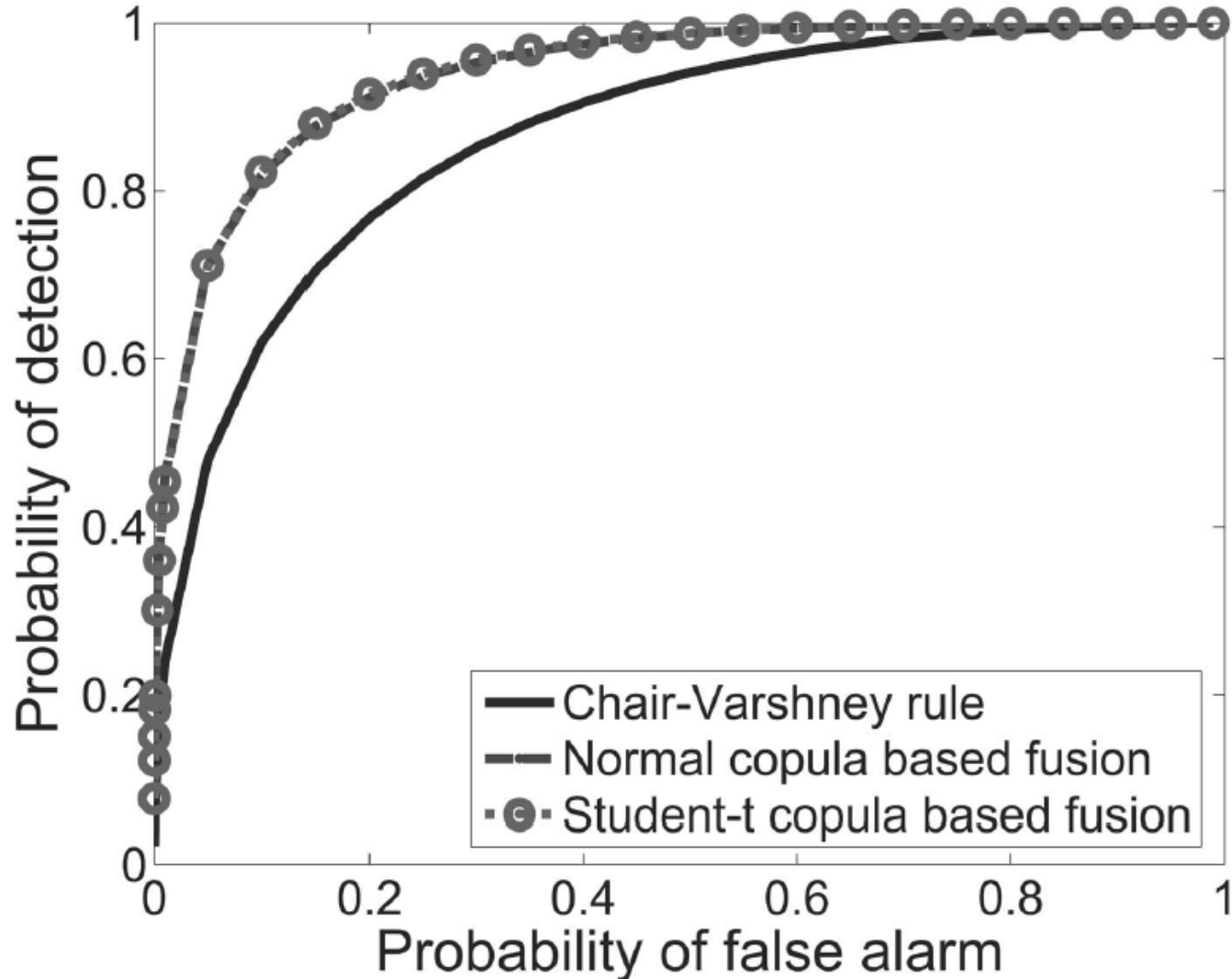
$$i = 1, 2; n = 1, \dots, N$$

Background radiation

Signal from radioactive material

▶  $s_{in}^j \sim$  Count model  $\Rightarrow z_{in} \sim$  Infinite Gaussian Mixture

# Distributed Detection Example: Radiation Detection – ROC (Poisson Model)



# Copula-based Location Estimation

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- ▶ Given the intensity of a radiating source  $A_0$  and its location  $(x_0, y_0)$ ,

$$\boldsymbol{\theta} = [A_0, x_0, y_0]$$

- ▶ Find,

$$\hat{\boldsymbol{\theta}} = \arg \max \left[ \sum_{n=1}^N \sum_{l=1}^L \log(f(v_{in} | \boldsymbol{\theta})) + \sum_{n=1}^N \log c(\mathbf{F}(\cdot | \boldsymbol{\theta}) | \boldsymbol{\phi}) \right]$$

- ▶ Copula parameter is estimated as a nuisance parameter

A. Sundaresan and P. K. Varshney, "Location estimation of a random signal source based on correlated sensor observations," *IEEE Trans. Signal Process.*, vol. 59, no. 2, pp. 787–799, 2011.

# Source Localization: Model Fusion

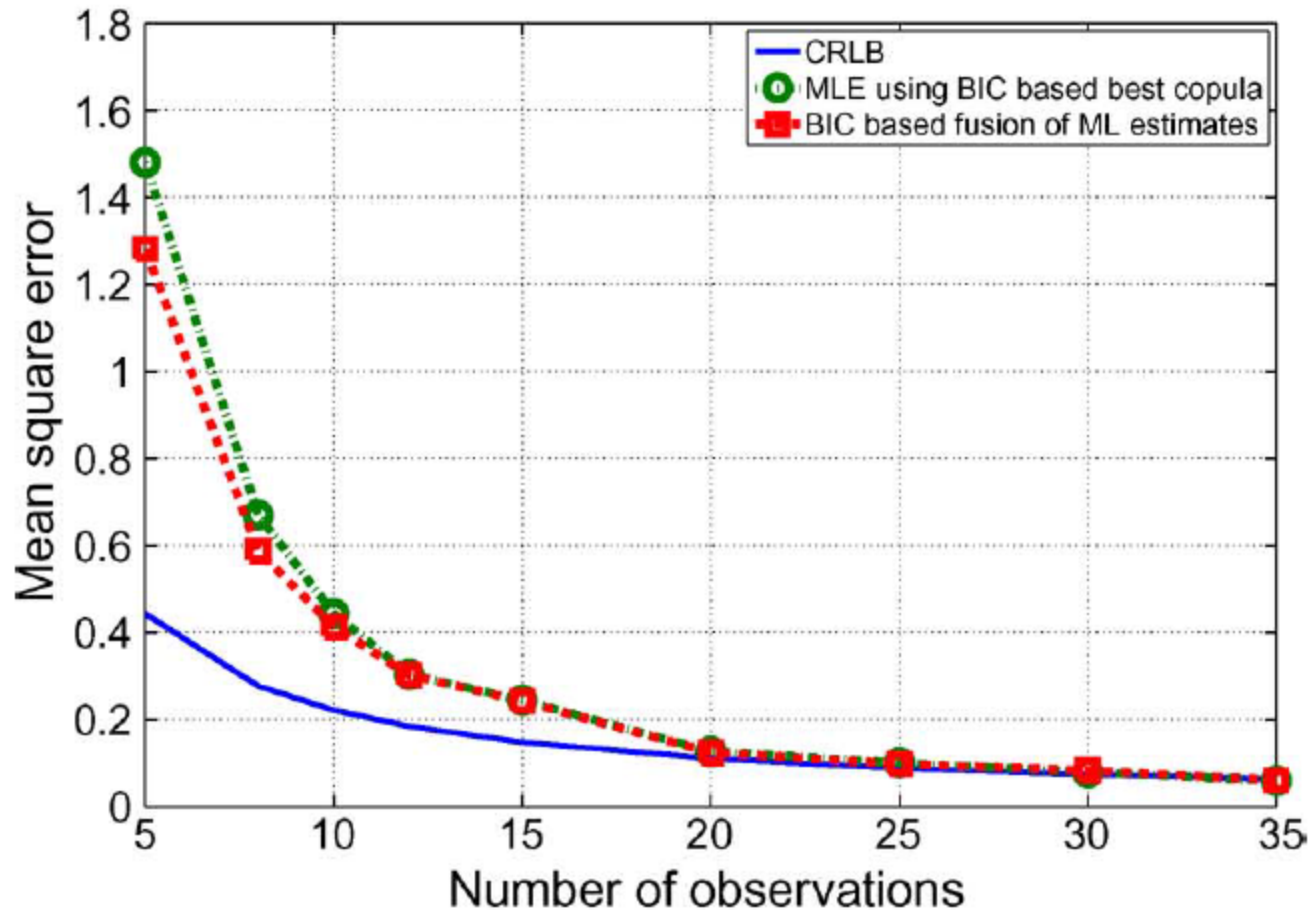
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- ▶ Using the same data for statistical inference and model selection leads to *selection bias*
- ▶ Model fusion can reduce selection bias
- ▶ Uses weighted sum of all  $K$  models, including those rejected

# Results:

## Localization of an isotropic radiating source

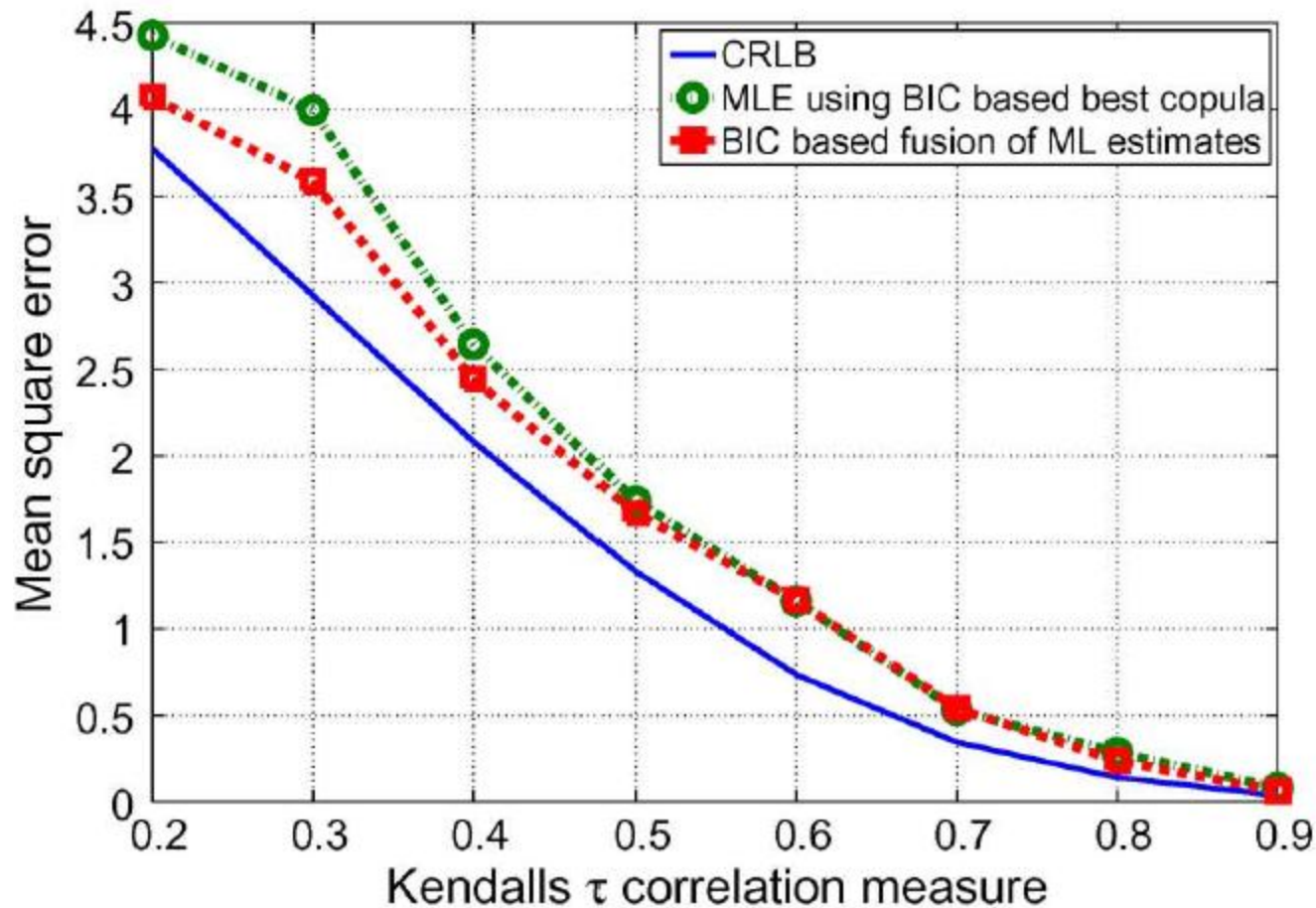
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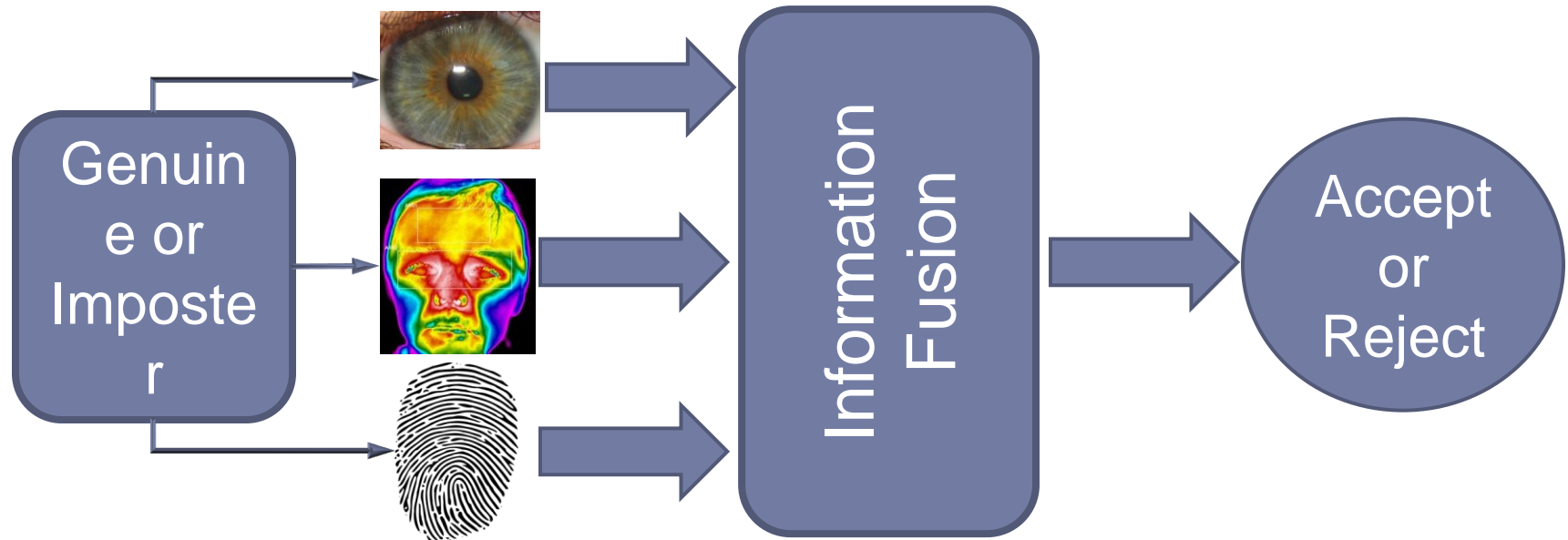
# Results:

## Localization of an isotropic radiating source

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# Classification: Application to Multi-biometrics



- ▶ Data from NIST
  - ▶ Two face-matchers with different performance and statistical properties
- ▶ Data partitioning: Randomized test/train partitions
- ▶ Fusion of algorithms

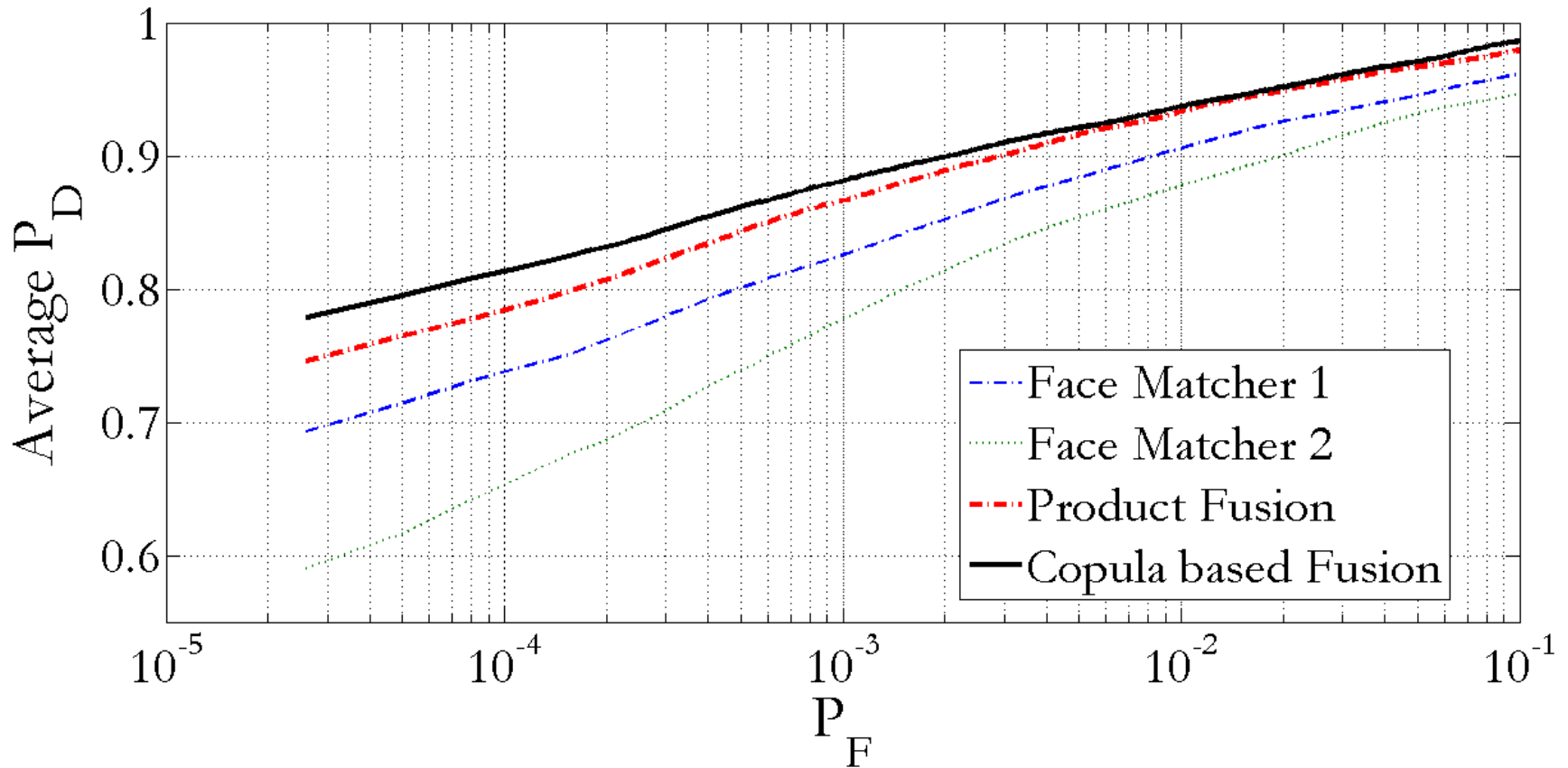
Iyengar et al., *IEEE Trans. Signal Process.*, Vol 59, No. 5, pp. 2308 – 2319, 2011.

Also see S. G. Iyengar, P. K. Varshney and T. Damarla, "Biometric Authentication: A Copula Based Approach," in *Multibiometrics for Human Identification*, B. Bhanu and V. Govindraju, Eds. Cambridge Univ. Press



# Multi-biometrics: Results

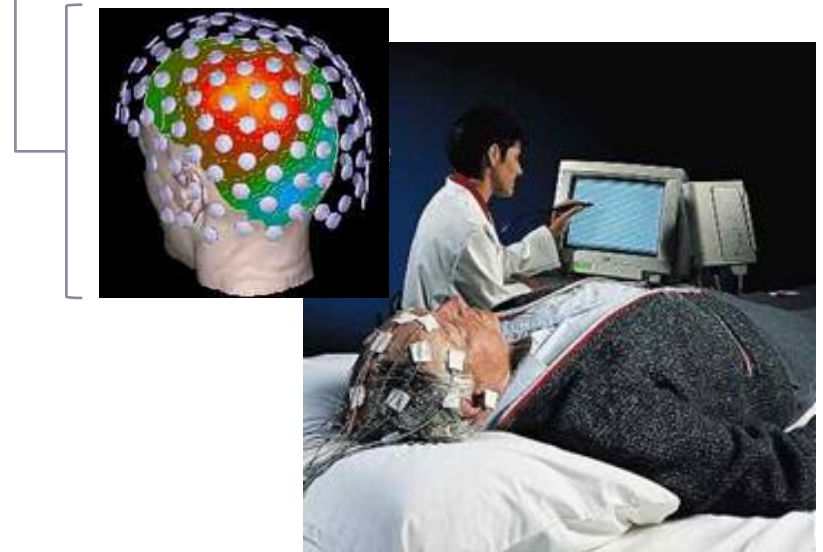
Copula selected using AUC based methodology



Receiver Operating Characteristic (ROC)

# Quantification of Neural Synchrony

- ▶ Neural synchrony: co-movement of neural activity
- ▶ Why do we care?
  - ▶ Suggestive of neurophysiological disorders such as **Alzheimer's Disease** and epileptic seizures
  - ▶ Useful for studying brain connectivity and neural coding
- ▶ How do we quantify synchrony?
- ▶ Limitations of existing measures
  - ▶ Existing measures such as Granger causality measure only the linear relationship
  - ▶ Information theoretic measures such as mutual information are constrained to be bivariate
- ▶ Copula based multi-information developed to alleviate both limitations



# Copula-based Multi-information

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- ▶ Multi-information is used as a global synchrony measure
- ▶ Joint density estimated using copula

$$\mathcal{I} = \int f \log \frac{f^p c(\cdot)}{f^p} = \mathbb{E}_f \log c(\cdot)$$

- ▶ Copula based estimate (for 2 sensors, and a time frame of  $m$  samples  $\rightarrow$  model order  $m$ )

$$\hat{\mathcal{I}}_h = \frac{1}{L} \sum_k \log h(u_{1k}, \dots, u_{1(k-m)}, u_{2k}, \dots, u_{2(k-m)})$$

- ▶  $h(\cdot)$  is the copula density chosen *a priori*

S. G. Iyengar, J. Dauwels, P. K. Varshney and A. Cichocki, "EEG Synchrony quantification using Copulas," *Proc. IEEE ICASSP*, 2010

# Early Diagnosis of Alzheimer's Disease

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- ▶ Neural synchrony can be used as a feature for classification
  - ▶ Drop in neural synchrony indicates possibility of Alzheimer's Disease (AD)
  - ▶ Increased neural synchrony → Epilepsy
- ▶ 25 patients with Mild Cognitive Impairment (MCI) vs. 38 age-matched control subjects
- ▶ All 25 patients developed mild AD later
- ▶ Inclusion of copula-based feature improves classification performance



# *Conclusion*

Summary  
References

# Summary

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- ▶ Copula based inference has diverse applicability
  - ▶ Fusion of multimodal sensors *and* homogeneous sensors
  - ▶ *Multi-algorithm* Fusion – Approach discussed for multi-biometrics falls under this category
  - ▶ *Multi-classifier* Fusion – Fusing different classifiers
- ▶ A theory for signal inference from dependent observations
  - ▶ Inclusive theory: independence is a limiting case
  - ▶ Signal Detection
  - ▶ Signal Classification
  - ▶ Parameter estimation
- ▶ Copula-based approach shows significant improvement over previously proposed techniques on real datasets

# References

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