

Wavefront sensors - 1

First example of wavefront sensor: Shack-Hartmann

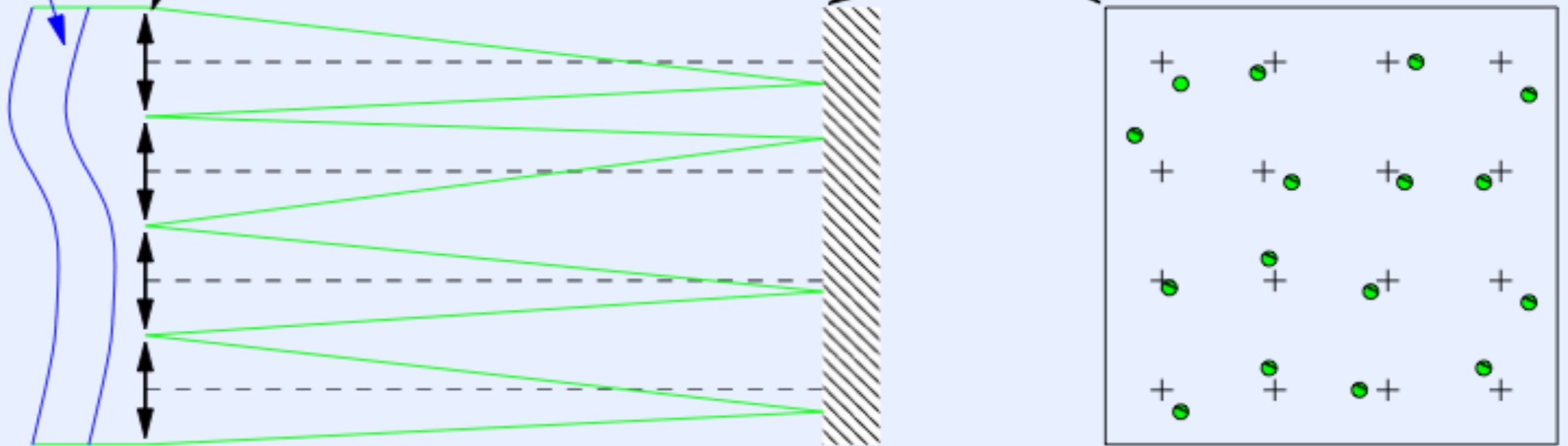
Front d'onde turbulent

Matrice de micro-lentilles

matrice CCD

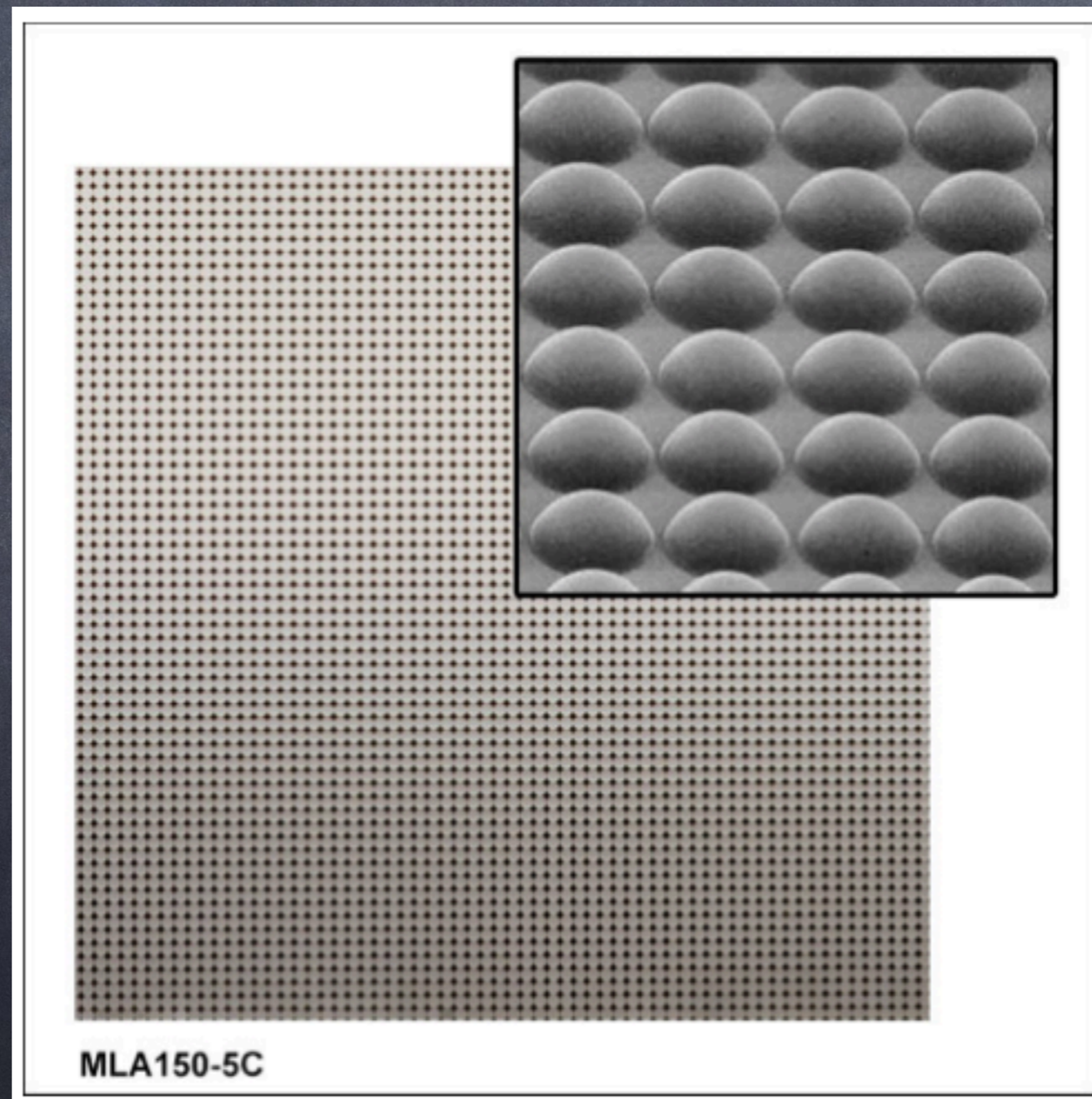
● spot turbulent

+ axe optique



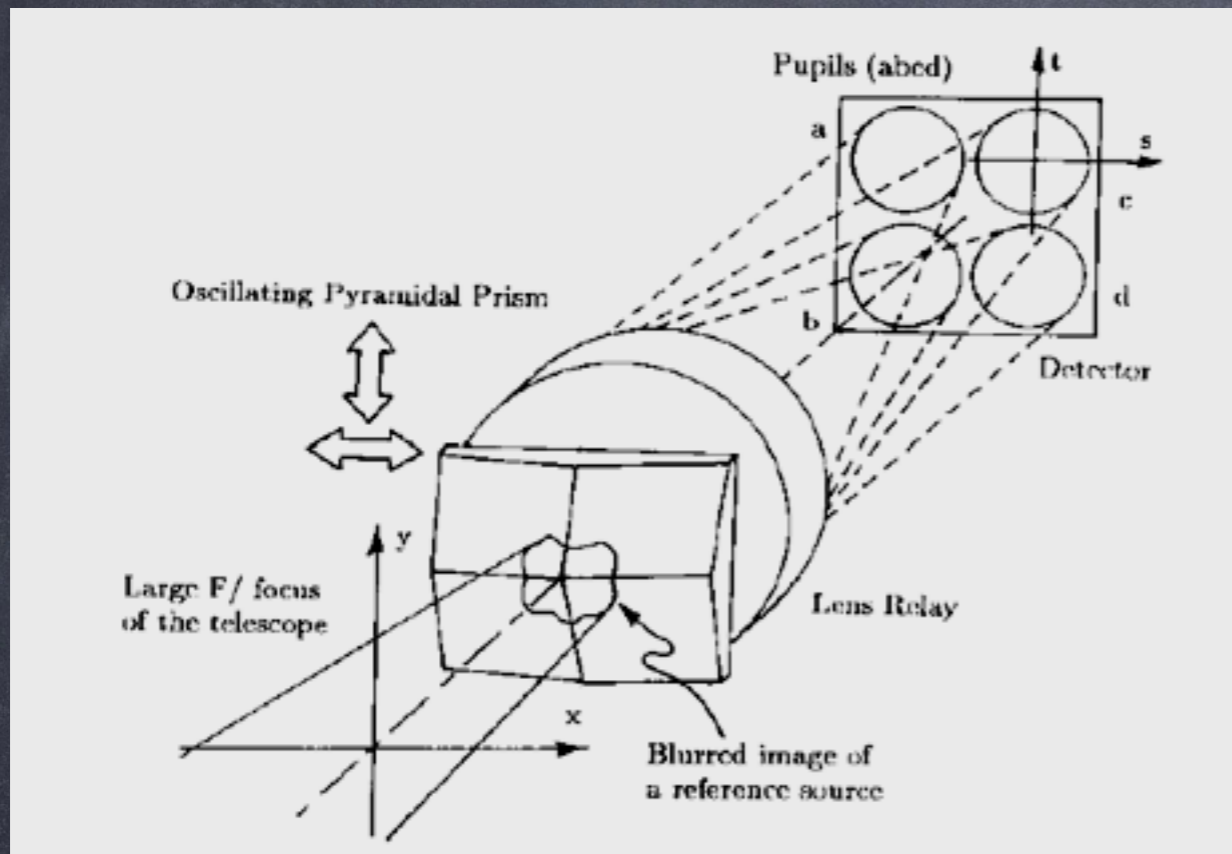
Wavefront sensors - 2

First example of wavefront sensor: Shack-Hartmann

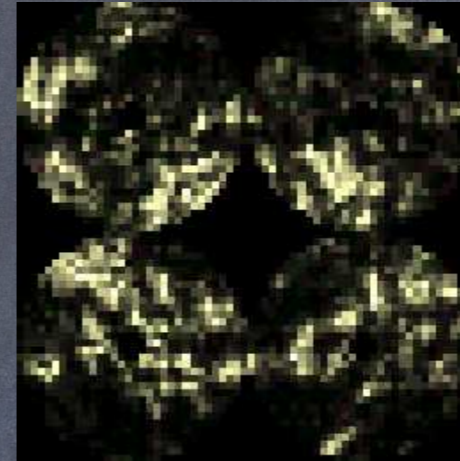


Wavefront sensors - 3

Another example: the Pyramid WFS



boucle ouverte

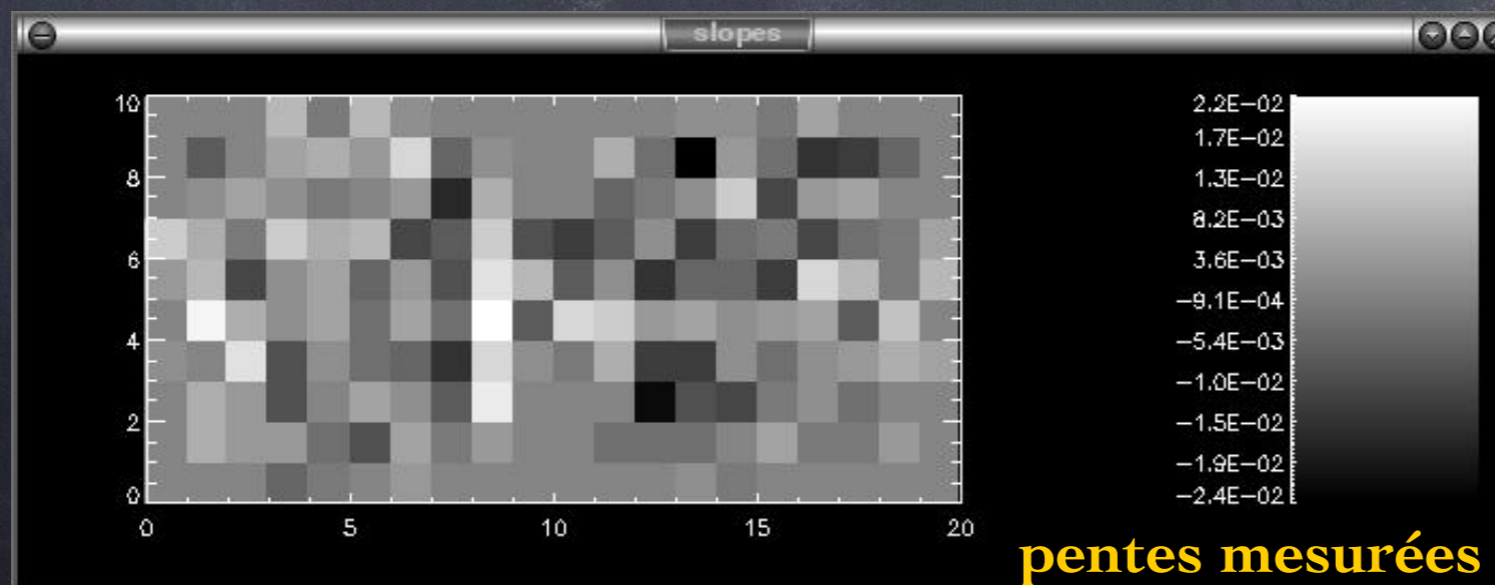


boucle fermée



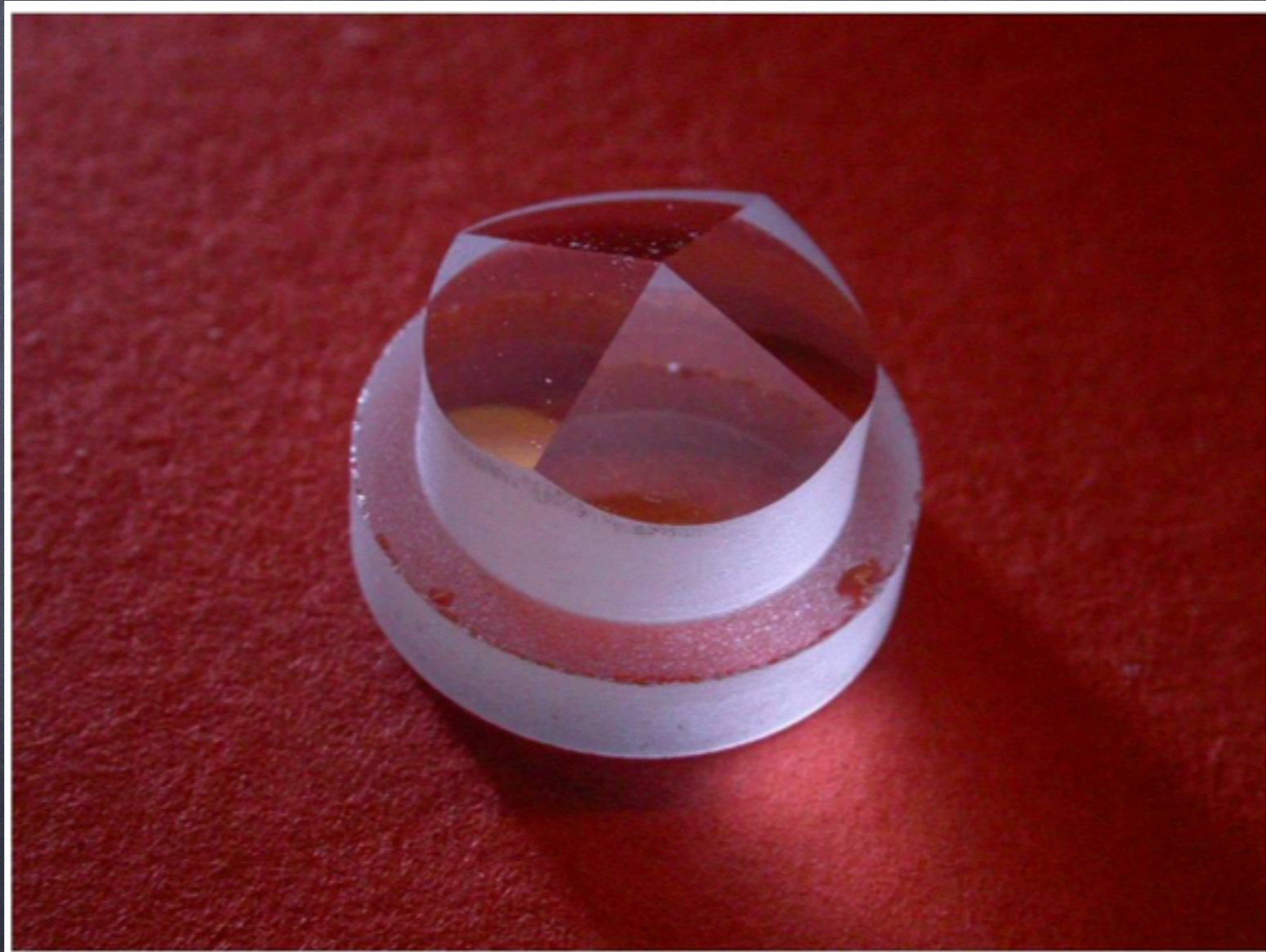
$$S_x(x, y) = \frac{(I_1 + I_4) - (I_2 + I_3)}{\sum_i I_i}$$

$$S_y(x, y) = \frac{(I_1 + I_2) - (I_3 + I_4)}{\sum_i I_i}$$



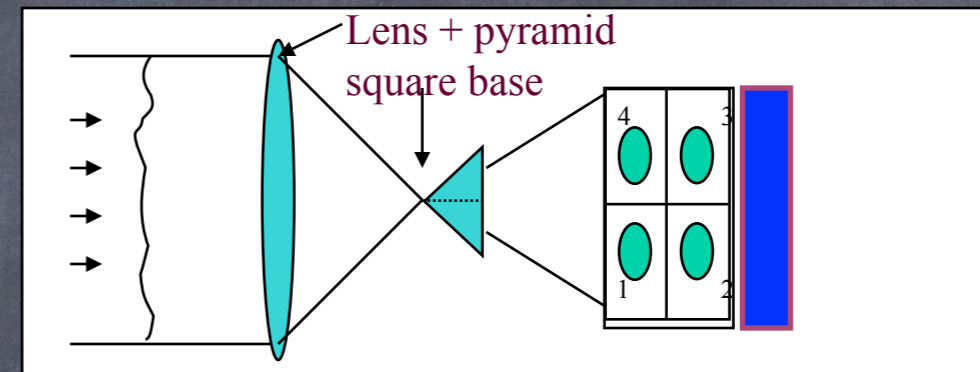
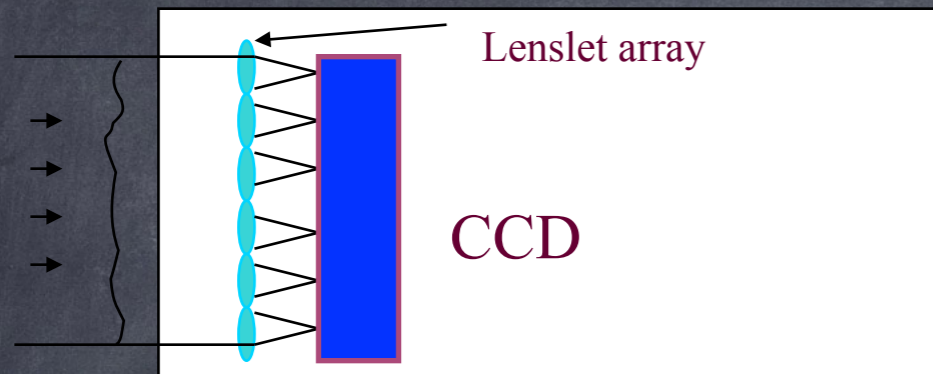
Wavefront sensors - 4

Another example: the Pyramid WFS



WH telescope's AO system

Wavefront sensors - 5



- SH: First on-sky AO results with COME-ON/VLT in 1989 [Rousset et al. 1990].
- Pyramid [Ragazzoni 1996], 2-mag. gain foreseen with respect to SH [Ragazzoni & Farinato 1999], confirmed by Monte-Carlo simulations [Esposito & Riccardi 2001].

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Pyramid vs. Shack-Hartmann, 1st round

- Rousset et al., 1989-1990: 1st results of a SH WFS on sky on the VLT (COME-ON)
- Ragazzoni, 1996: proposal of a pyramid WFS
- Ragazzoni & Farinato, 1999: theoretical gain of 2 mag. (in limiting mag.)
- Esposito & Riccardi, 2001: gain confirmed by numerical simulations (but in open-loop and not the whole AO error budget)
- Carbillet et al., 2003: gain in limiting mag. confirmed (close loop & whole AO error), but also in the bright-end (lower aliasing!), from end-to-end simulations (for FLAO@LBT).

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Pyramid vs. Shack-Hartmann, 2nd round

- Poyneer & Macintosh, 2004: spatial filtering of the SH WFS (lower aliasing error)
- Nicolle et al., 2004: optimized calculus of the SH signals (lower measurement error)
- Fusco et al., 2005: spatial filtering+optimized calculus => SH at the level of the Pyramid (and less uncertainties on stability and robustness...)
- Vérinaud et al., 2005 (in the framework of XAO and the ELT): Pyramid better close to optical axis, SH 'à la Fusco' better far from it.

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Pyramid vs. Shack-Hartmann, 2nd round

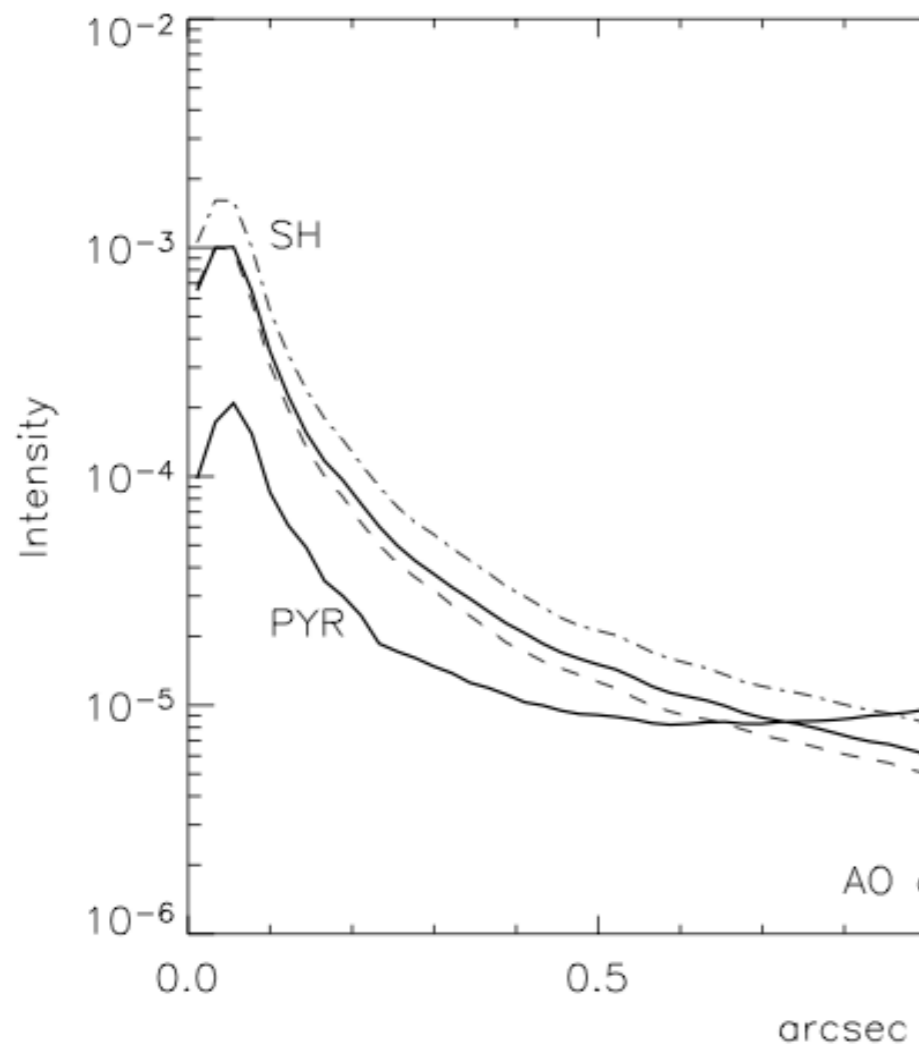


Figure 3. Circularly averaged residual halo (20 photons per sub-aperture) for the SFSH (SR = 0.946) and the PS (SR = 0.955) (solid line) and the WCOG, 20 photons per sub-aperture (dotted line).

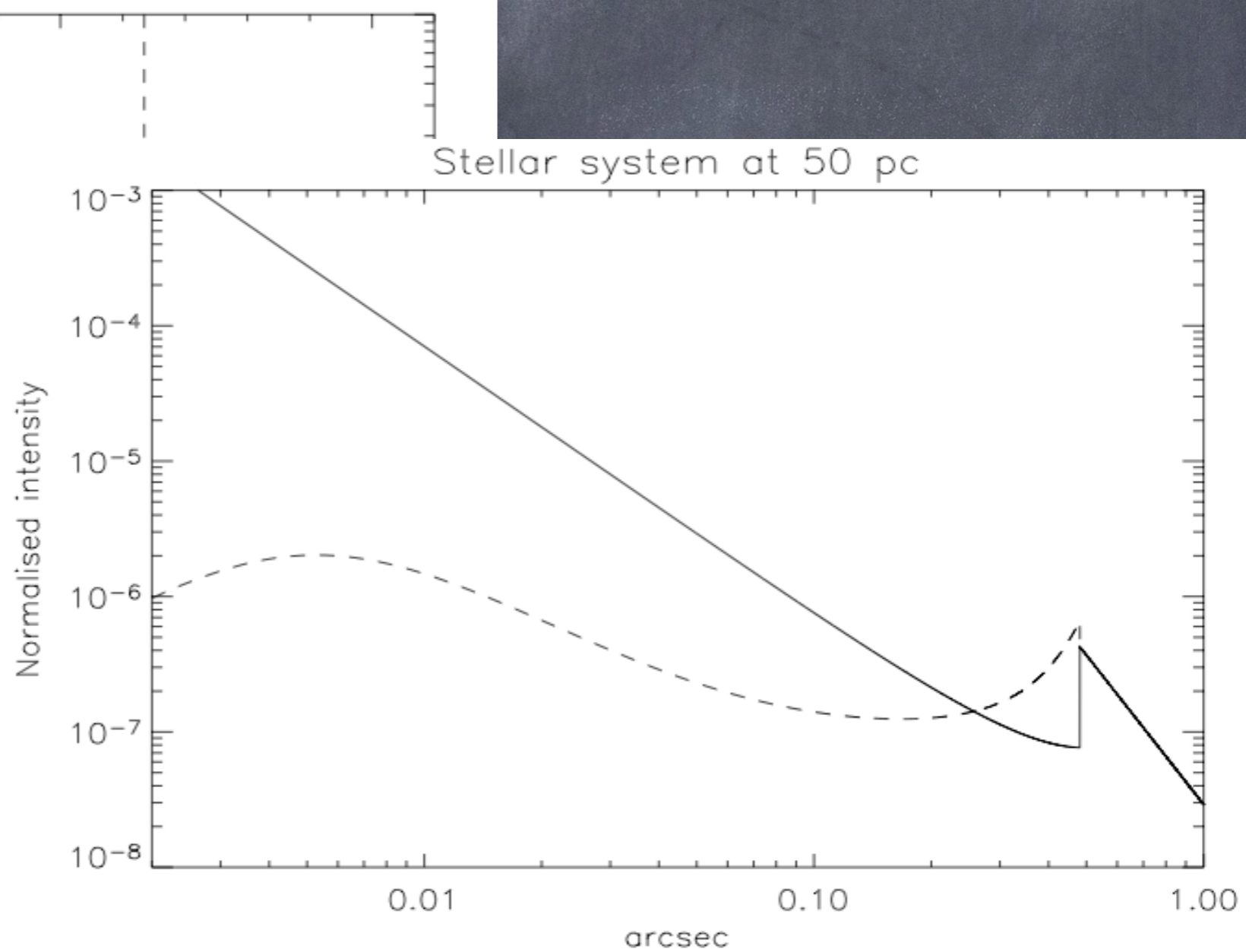


Figure 7. Residual halo in the R band for a SFSH-based system (solid line, SR = 0.79) and a PS-based system (dashed line, SR = 0.81) with a 15-cm actuator pitch on a 100-m telescope. The guide star V magnitude is 8.2, seeing = 0.7 arcsec, $\tau_0 = 3$ ms, frame rate = 4 kHz.

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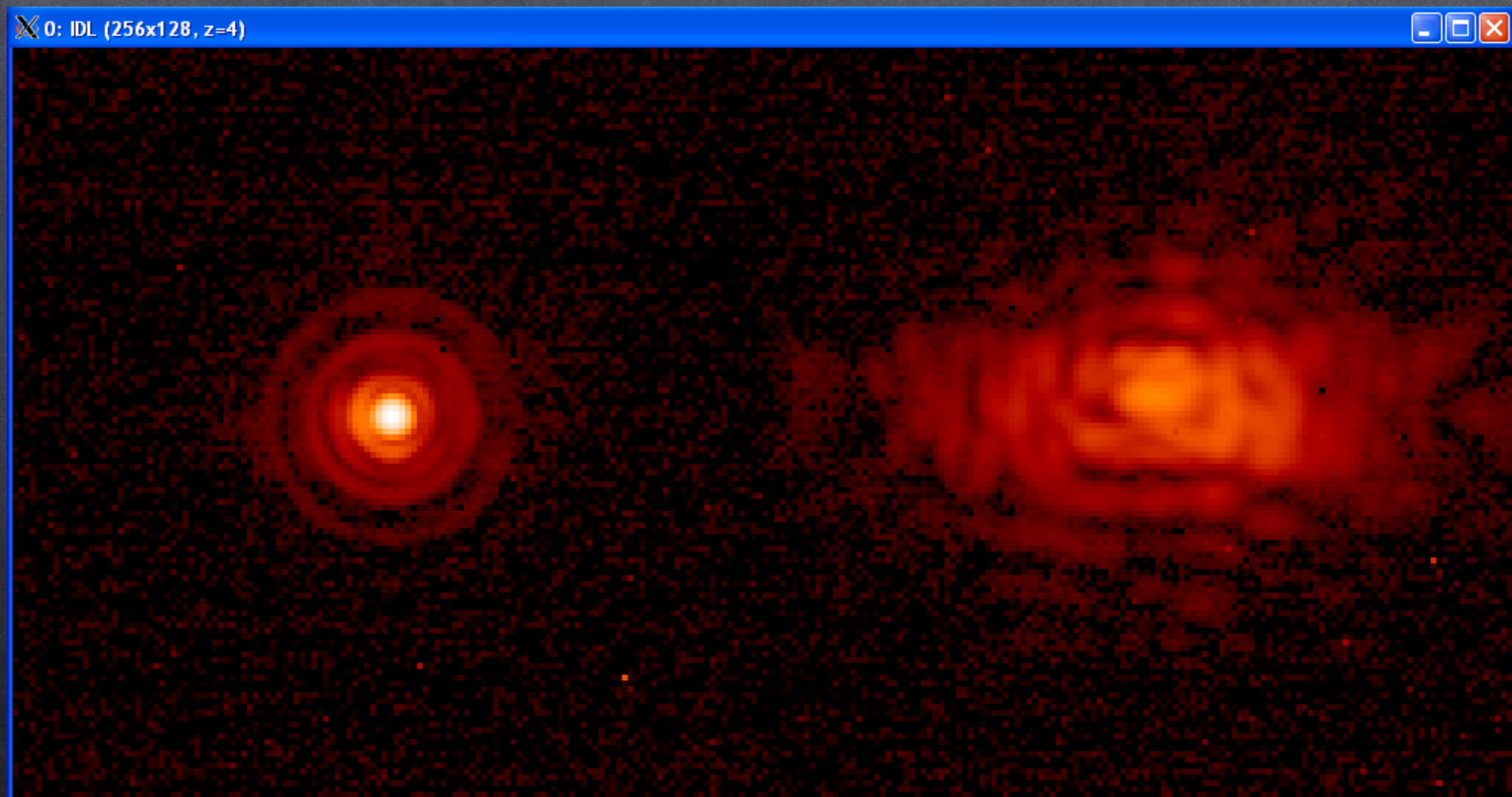
Pyramid vs. Shack-Hartmann, 3rd round

Press release (may/june 2010): LBT achieves
breakthrough with adaptive optics ! ([http://
oldweb.lbt.o.org/AO/AOpressrelease.htm](http://oldweb.lbt.o.org/AO/AOpressrelease.htm))

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Pyramid vs. Shack-Hartmann, 4th round

(2014)



Deformable correctors - 1

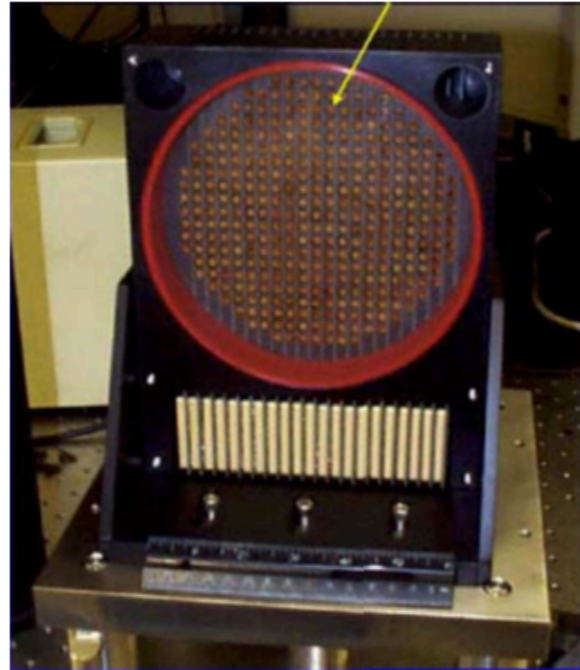
- Different technologies for correctors:
 - piezo-stacked arrays
 - piezo-electric bimorph mirrors
 - MEMS
 - voice-coil adaptive secondary mirrors (ASM)
 - multi-actuator adaptive lens (MAL) (!)
- Different coefficients for the fitting error, different strokes, different possible bandwidths, different possible number of modes, possible hysteresis, etc.

Deformable correctors - 2

146mm clear aperture

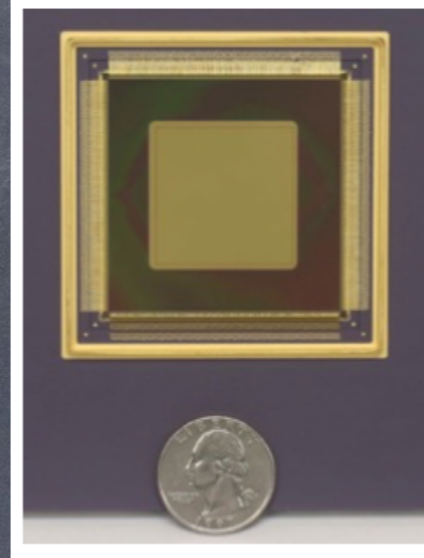


349 actuators on 7 mm spacing



Kinetics @ Keck

@Boston MC



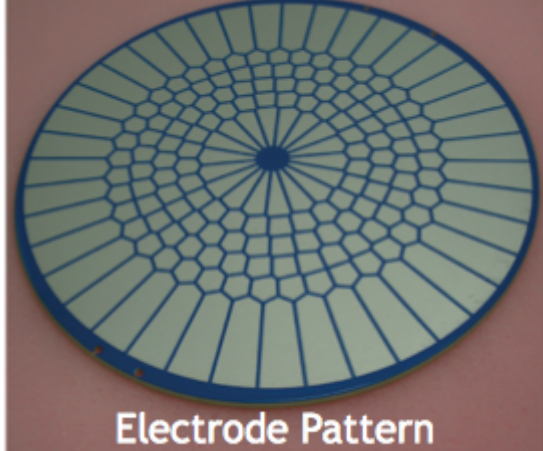
MEMS

Voice-coil ('adaptive secondary')

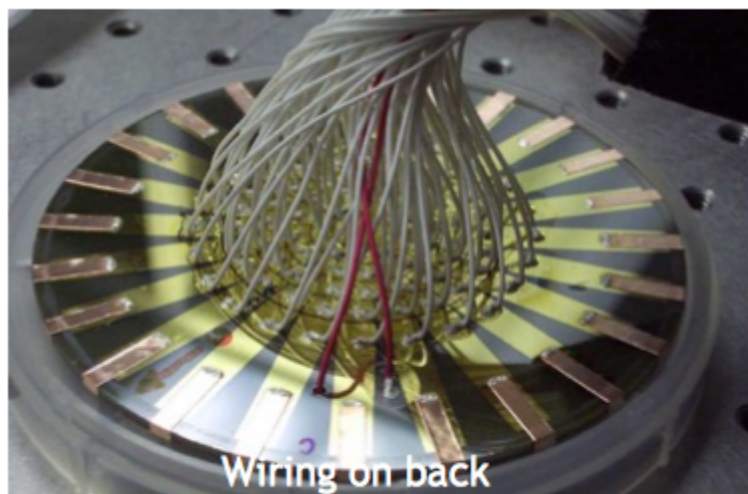
Piezo-stacked array

Bimorph

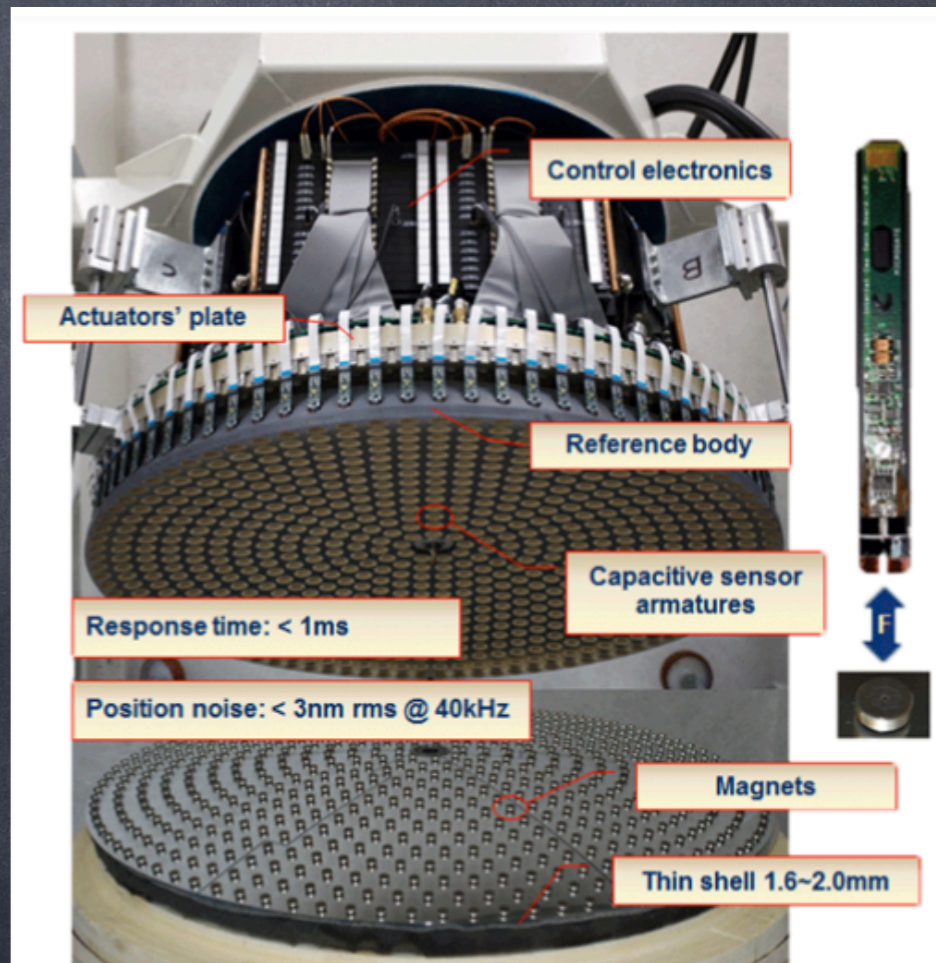
Credit: CILAS



Electrode Pattern



Wiring on back



- Control electronics
- Actuators' plate
- Reference body
- Capacitive sensor armatures
- Magnets
- Thin shell 1.6~2.0mm

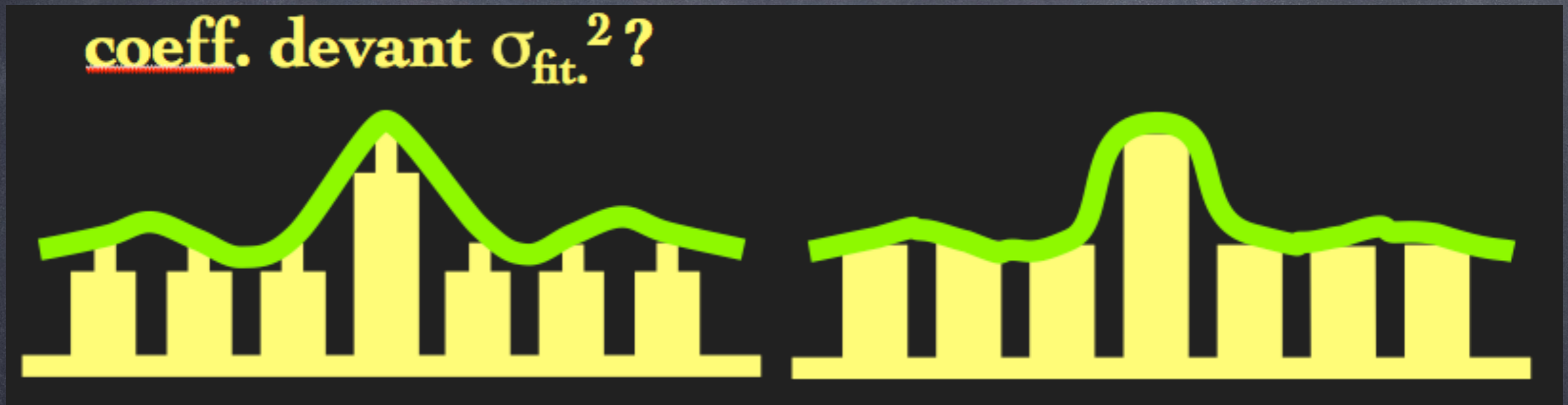
Response time: < 1ms

Position noise: < 3nm rms @ 40kHz

(c) Micro gate

Deformable correctors - 3

- Different coefficients for the fitting error:



- Is the stroke enough ?
If not: necessity to add a tip-tilt mirror...

Deformable correctors - 4

- How many actuators for a given Strehl ratio ?
(considering a coeff. 0.3 for the fitting error)

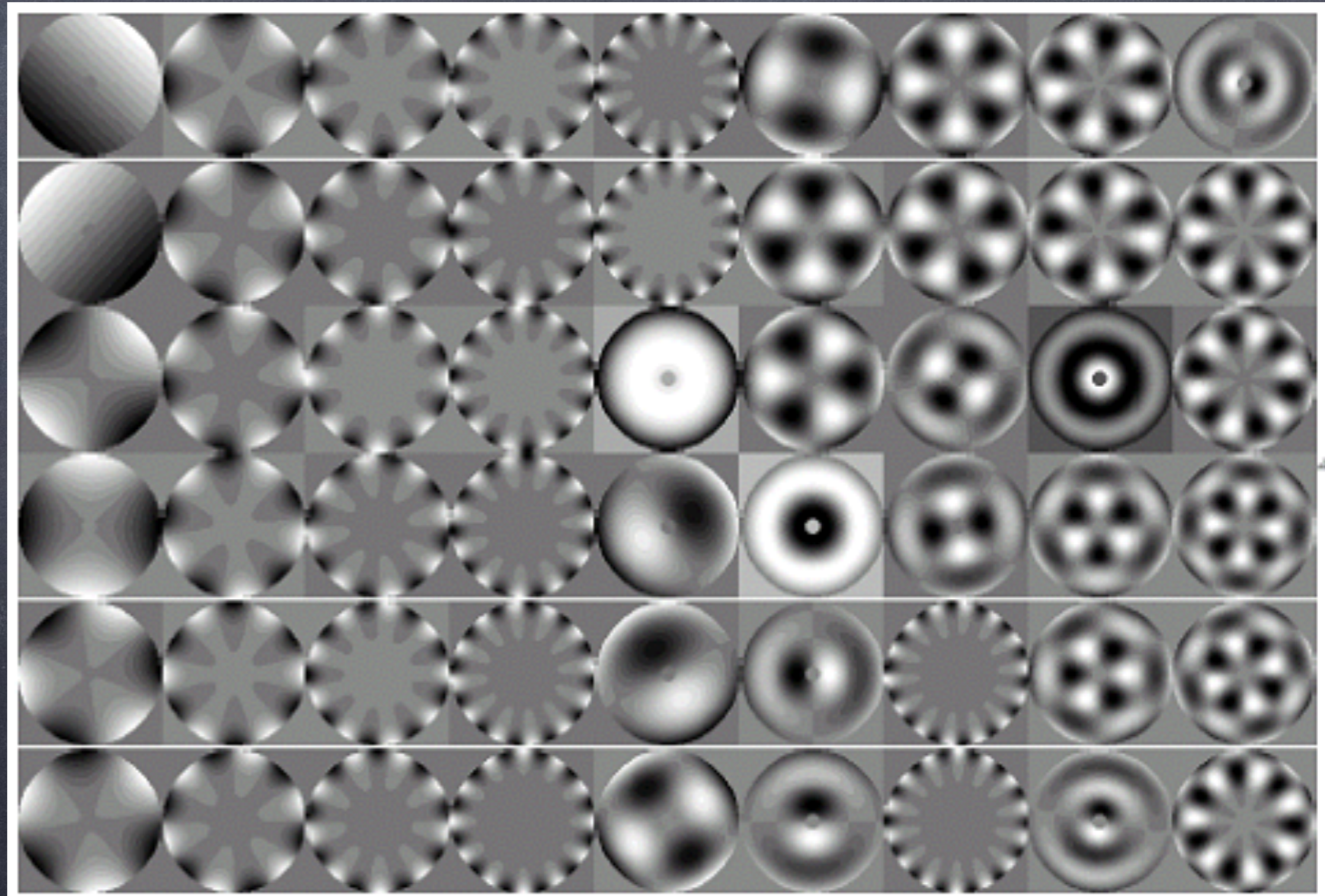
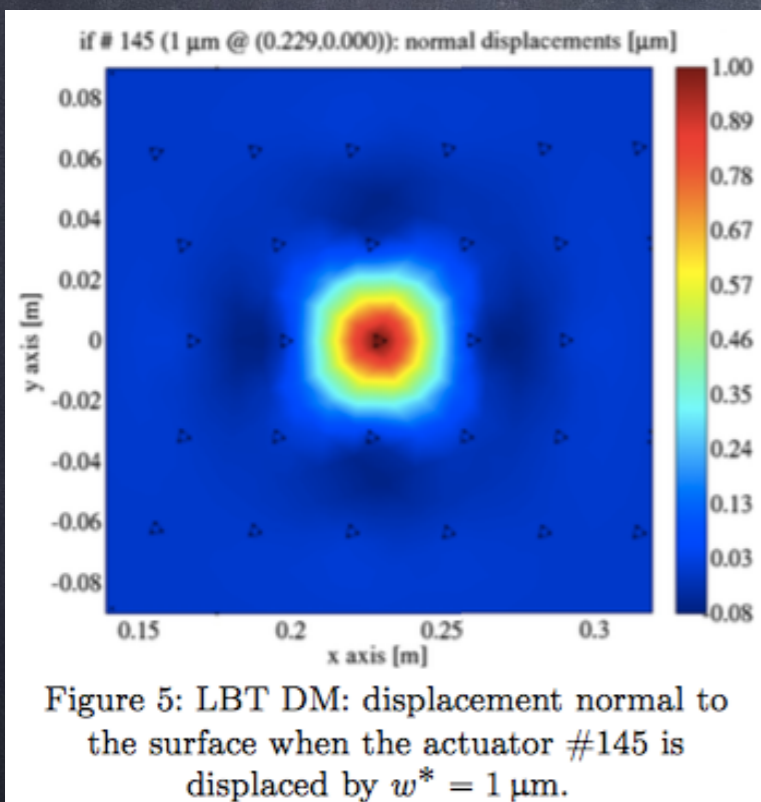
$$\sigma_{\text{fit.}}^2 = 0.3 \left(\frac{d_{\text{act.}}}{r_0} \right)^{5/3}$$

$$S_{\text{max}} = \exp(-\sigma_{\text{fit.}}^2)$$

- if $d = r_0$, then: $S_{\text{max}} = \exp(-0.3) \approx 0.74$
if $d = r_0/2$, then: $S_{\text{max}} = \exp(-0.3/2^{5/3}) \approx 0.91$

Deformable correctors - 5

- Influence functions \rightarrow mirror modes



Deformable correctors - 6

- An interesting case: the Adaptive Secondary Mirror (ASM) technology developed for LBT [Brusa et al. 2003]

